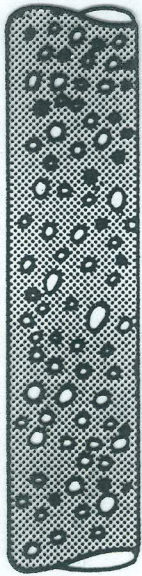


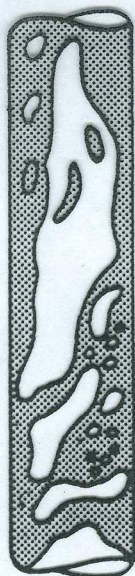
# Flow patterns in vertical gas-liquid flow



Bubble  
Flow



Slug or  
Plug  
Flow



Churn  
Flow

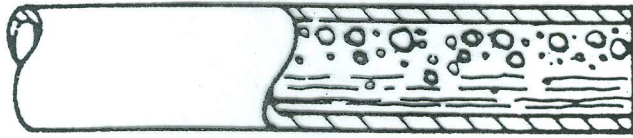


Annular  
Flow

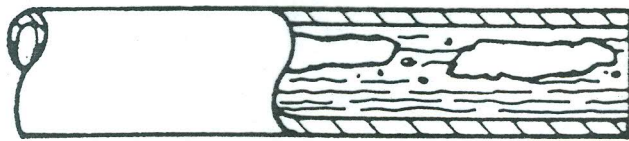


Wispy  
Annular  
Flow

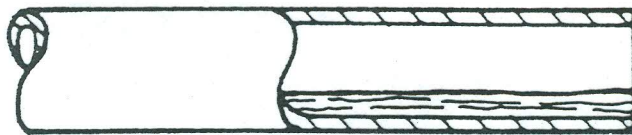
# Flow patterns in horizontal gas-liquid flow



Bubble flow



Plug flow



Stratified flow



Wavy flow

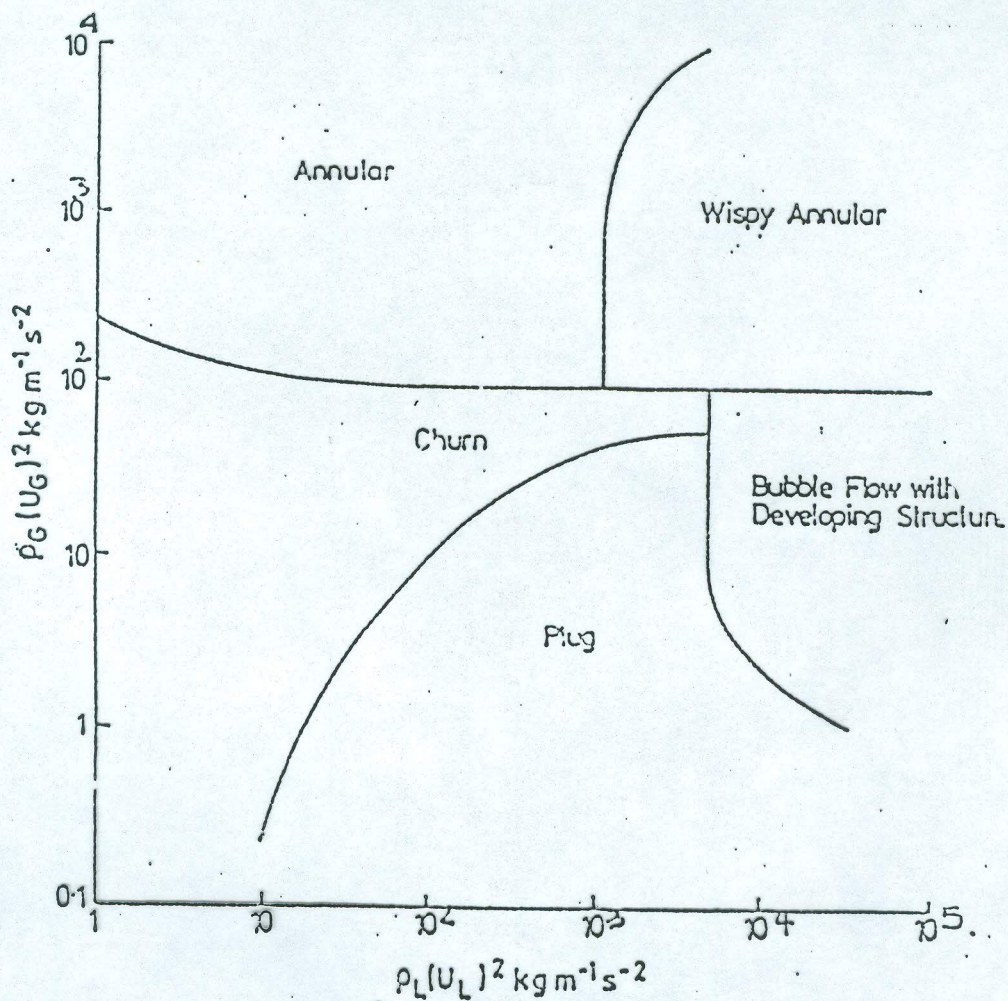


Slug flow



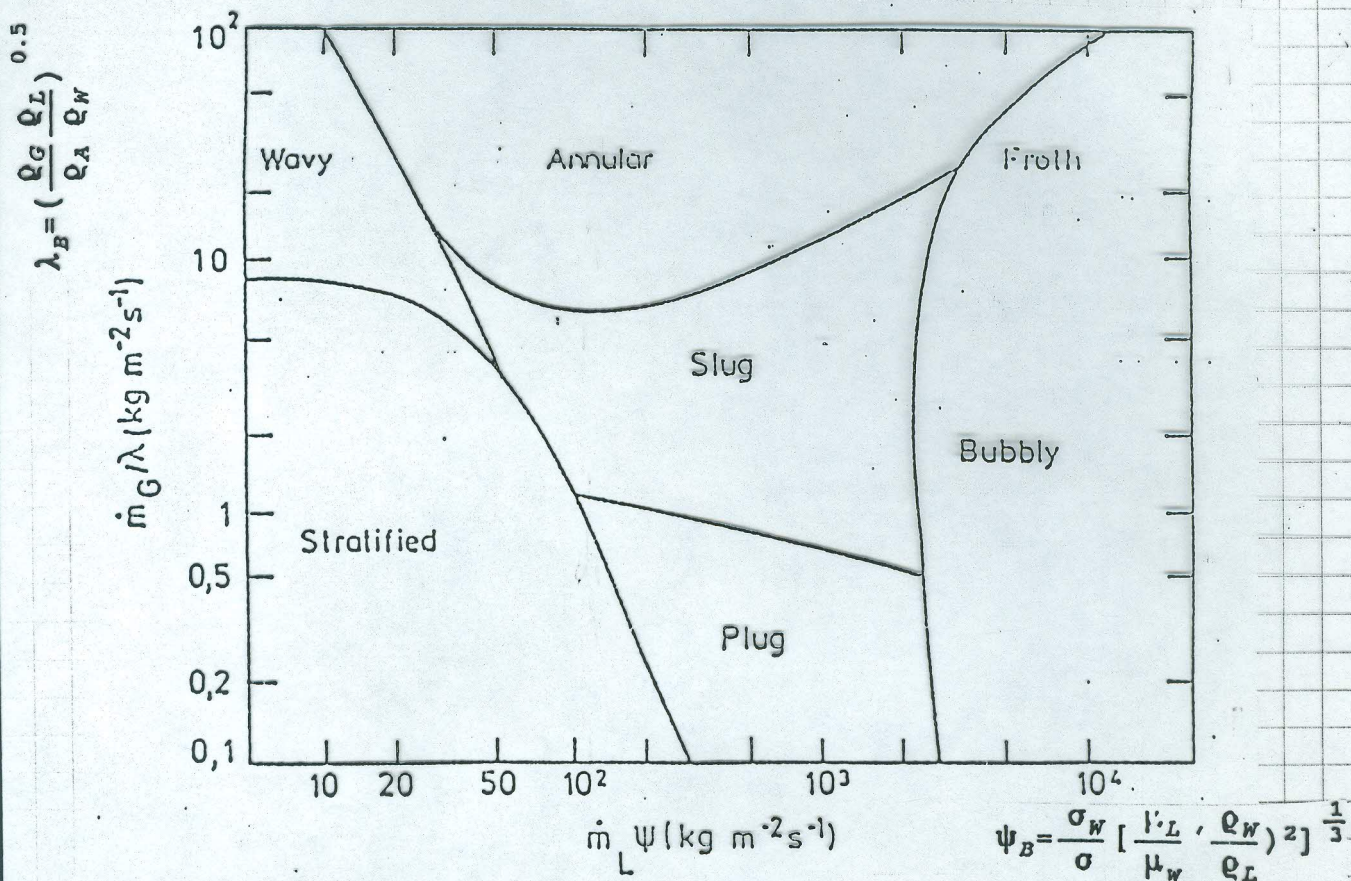
Annular flow

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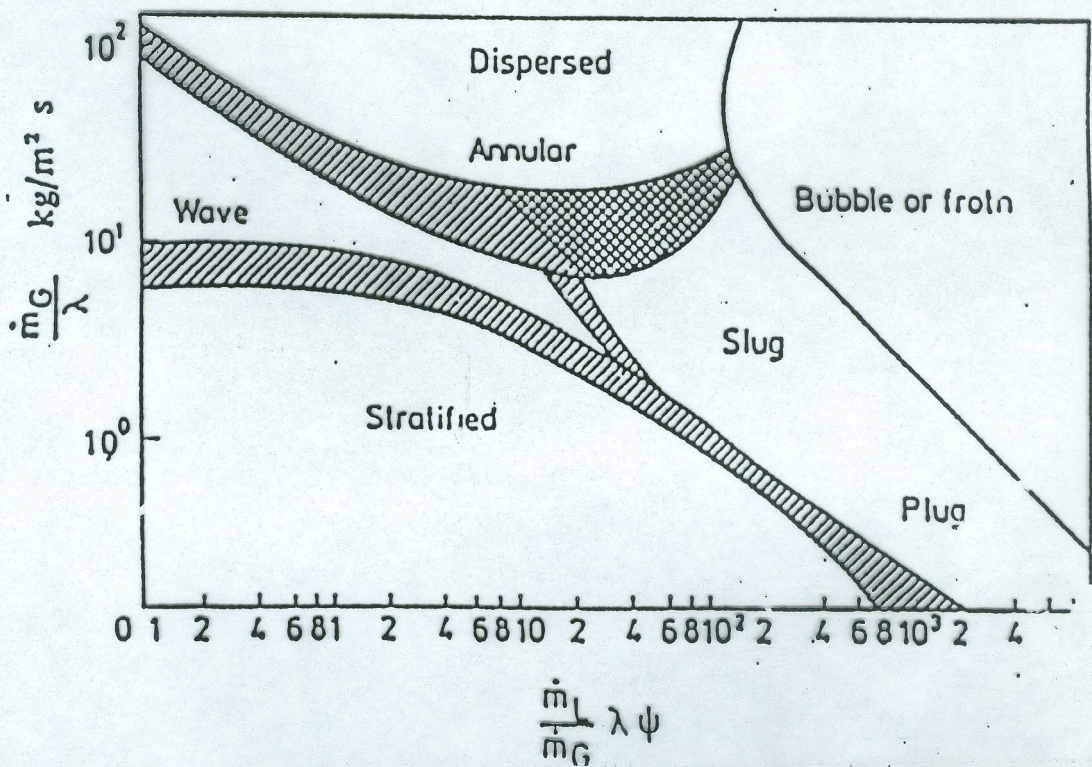


Σχήμα 4 : Ροϊκός χάρτης των Hewitt & Roberts για κάθετη μεταφορά αέρα-νερού

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Σχήμα 5 : Ροϊκός χάρτης του Baker για οριζόντια μεταφορά αέρα-νερού



Σχήμα 6 : Ο ροϊκός χάρτης του Baker όπως προτάθηκε από τον Bell

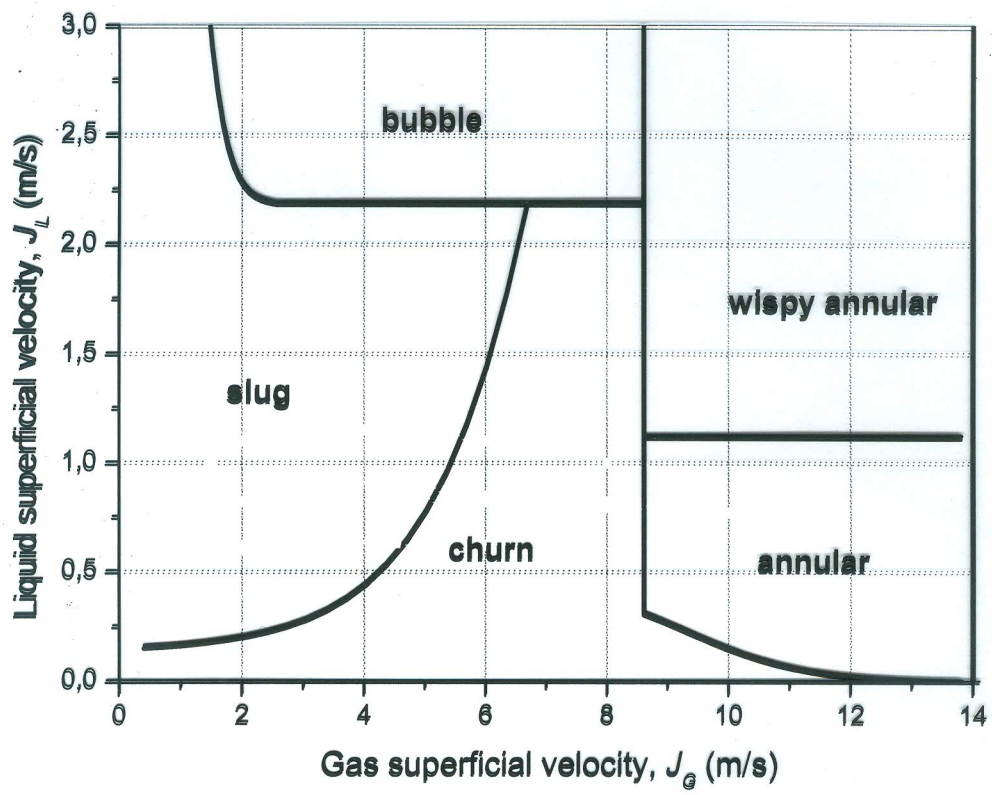


Figure 1. The new proposed two-phase flow regime map (Samaras-Margaris 2005).

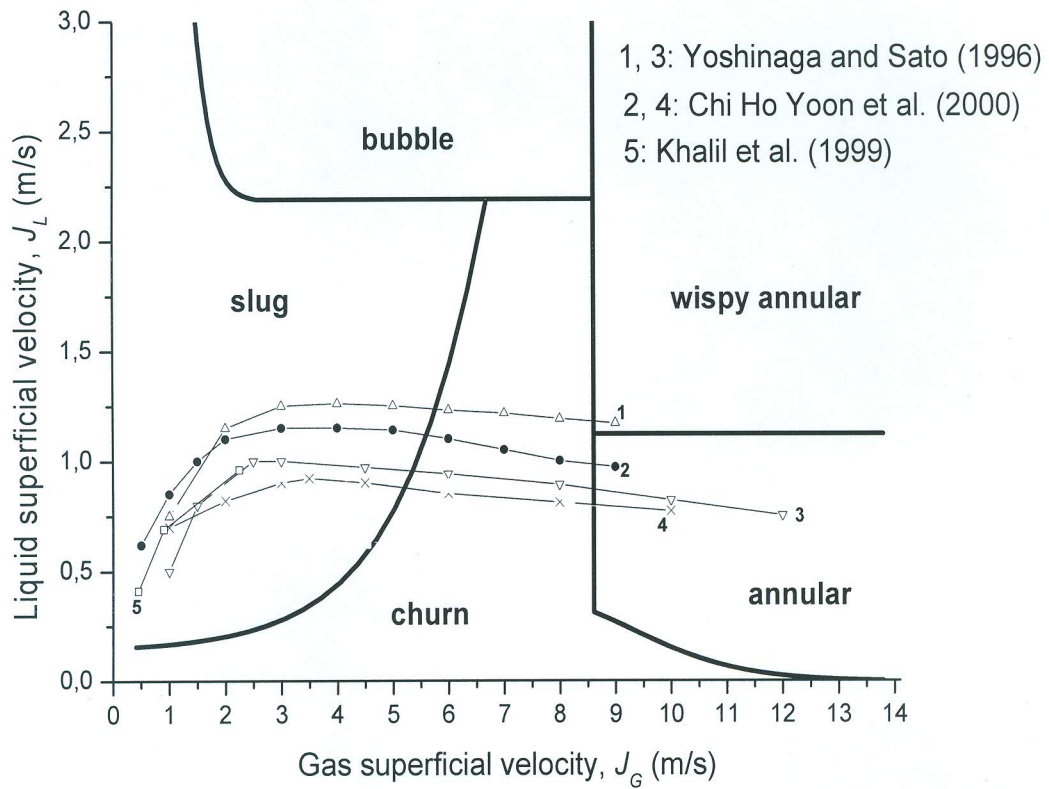


Figure 2. Presentation of airlift pump performance experimental data in  $J_L(J_G)$  map.

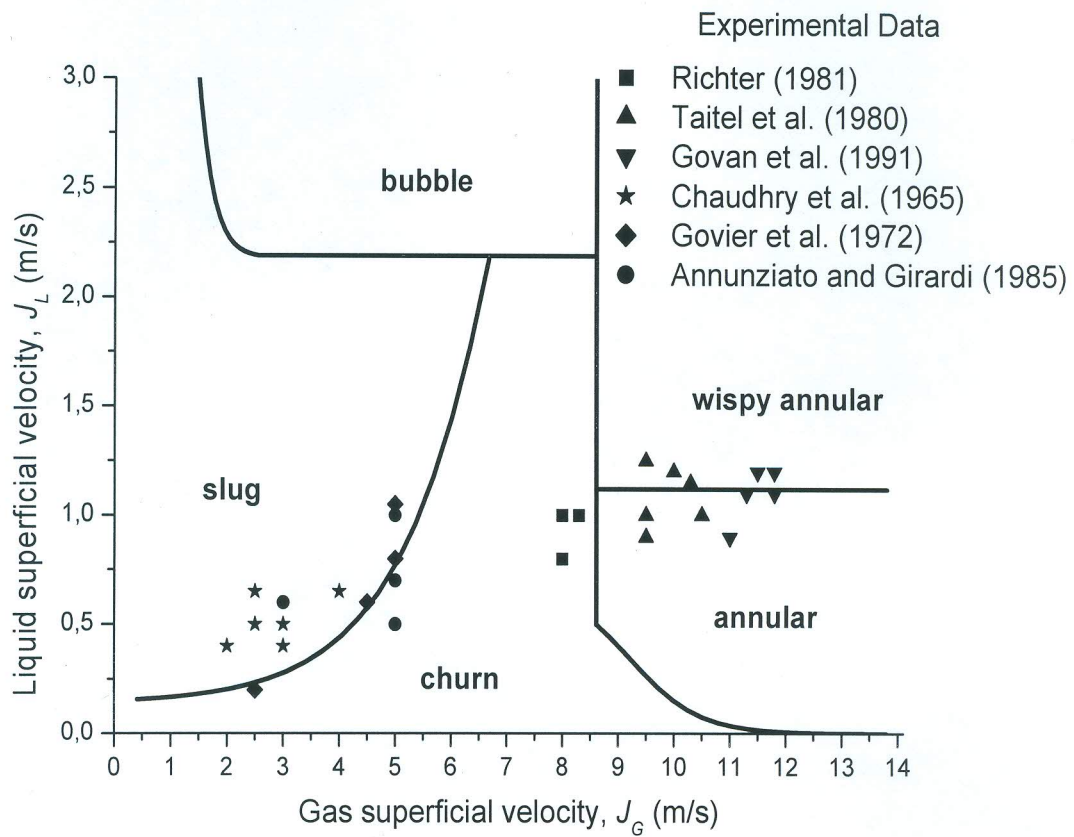


Figure 3. Validation of the regime map through regime transitions experimental data.

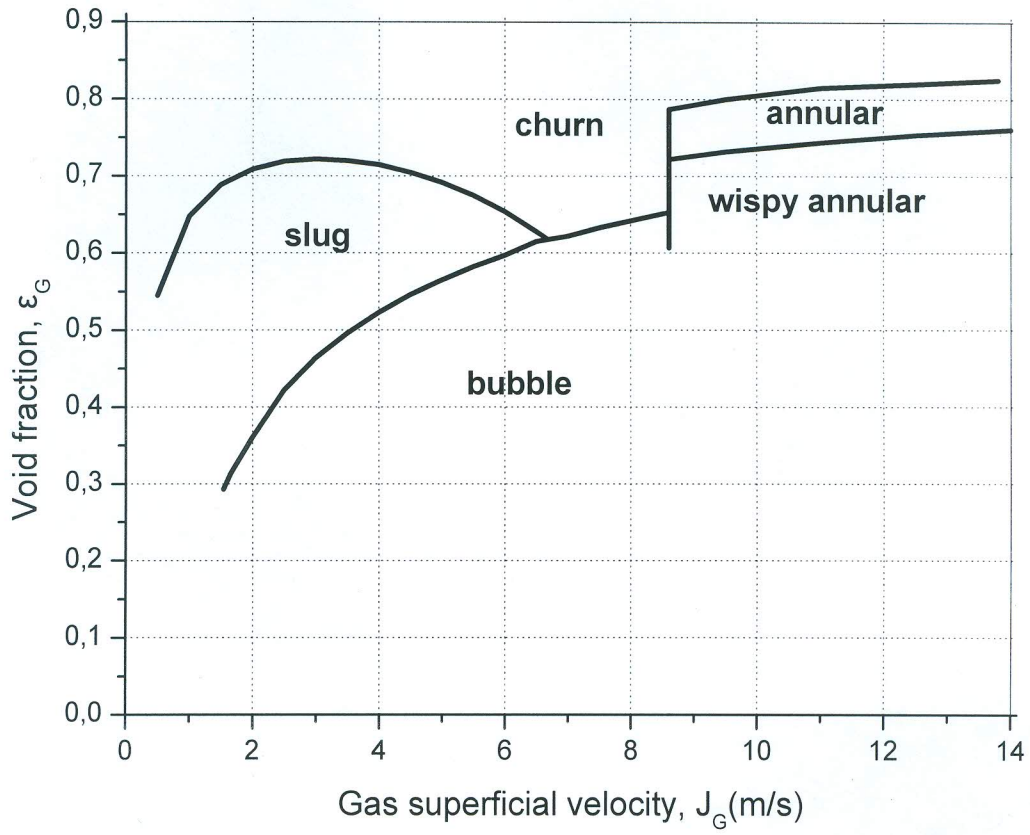


Figure 4. Two-phase flow regime map,  $\epsilon_G(J_G)$ .



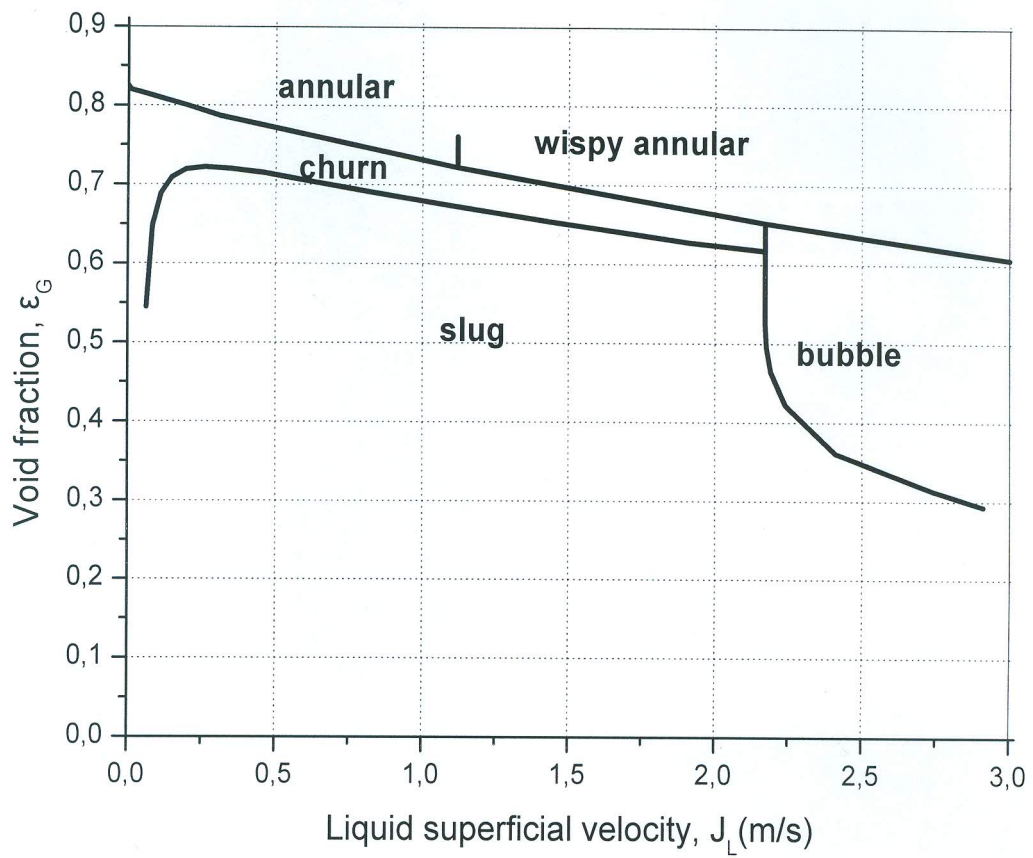


Figure 5. Two-phase flow regime map,  $\epsilon_G(J_L)$ .

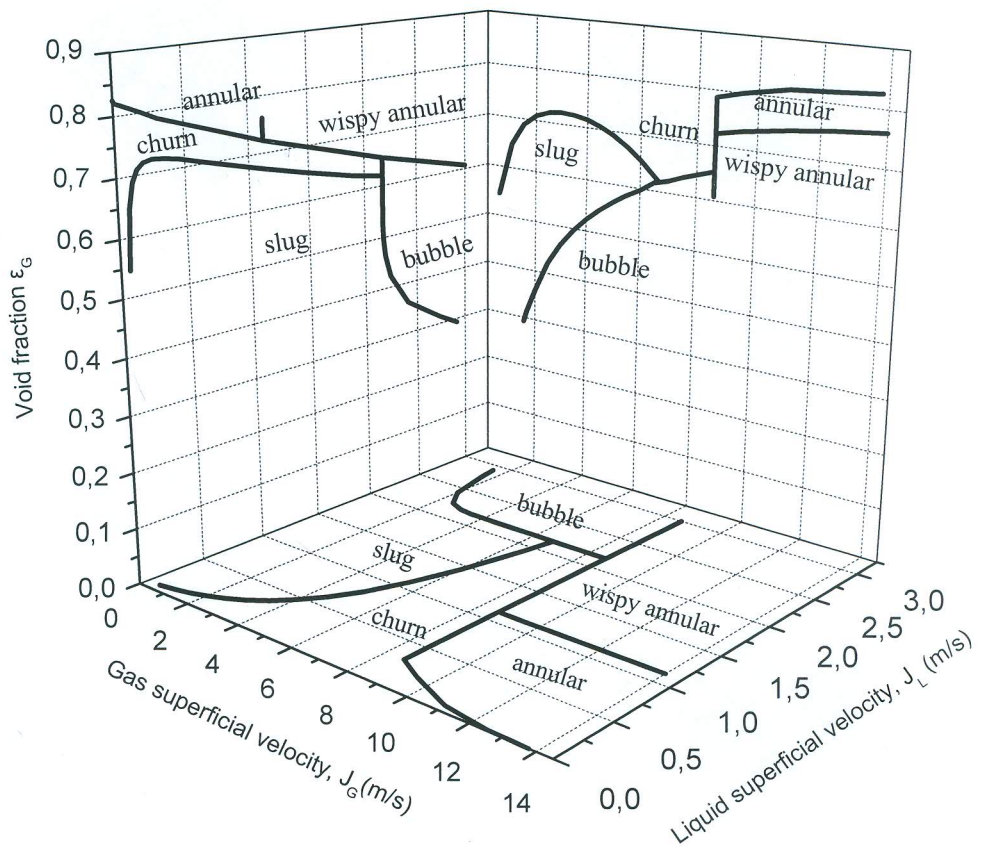
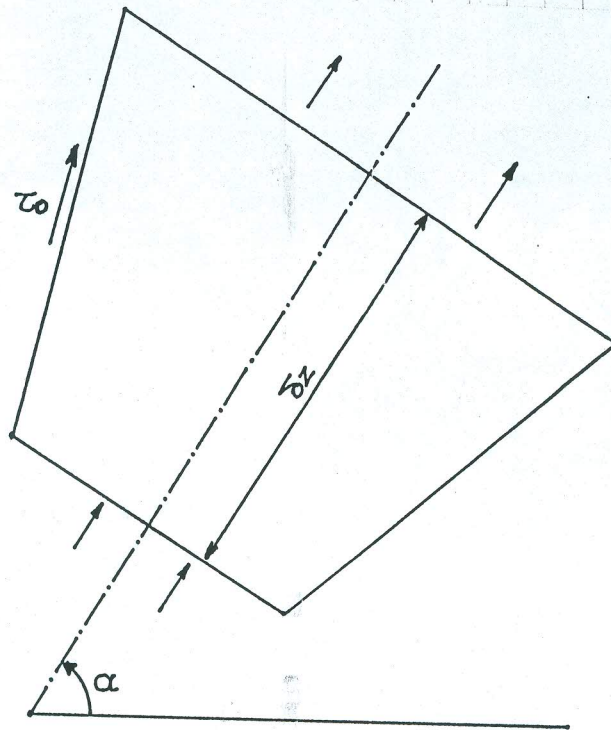


Figure 6. Three dimensional presentation of the three new regime maps.

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Σχήμα 3.2 : Στοιχειώδης ογκος ελέγχου ρευστού για το μοντέλο της ομογενούς ροής.

$$-\frac{dp}{dz} = \frac{\tau_0 P}{A} + \frac{d(m^2/\rho_{II})}{dz} + g\rho_{II} \sin \alpha$$

$$-\frac{dp}{dz} = -\frac{dp_f}{dz} - \frac{dp_a}{dz} - \frac{dp_g}{dz}$$

όπου  $dP_f = \tau_0 P/A$  : Πτώση πίεσης λόγω τριβής

$dP_a = d(m^2/\rho_{II})/dz$  : Πτώση πίεσης λόγω επιτάχυνσης

$dP_g = g\rho_{II} \sin \alpha$  : Πτώση πίεσης λόγω βαρύτητας.

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$$\frac{dP_g}{dz} = -g\rho_H \sin\alpha$$

$$\rho_H = \frac{\rho_G \rho_L}{x\rho_L + (1-x)\rho_G}$$

$$\frac{dP_g}{dz} = -g(-\rho_L a + \rho_L + a\rho_G) \rightarrow$$

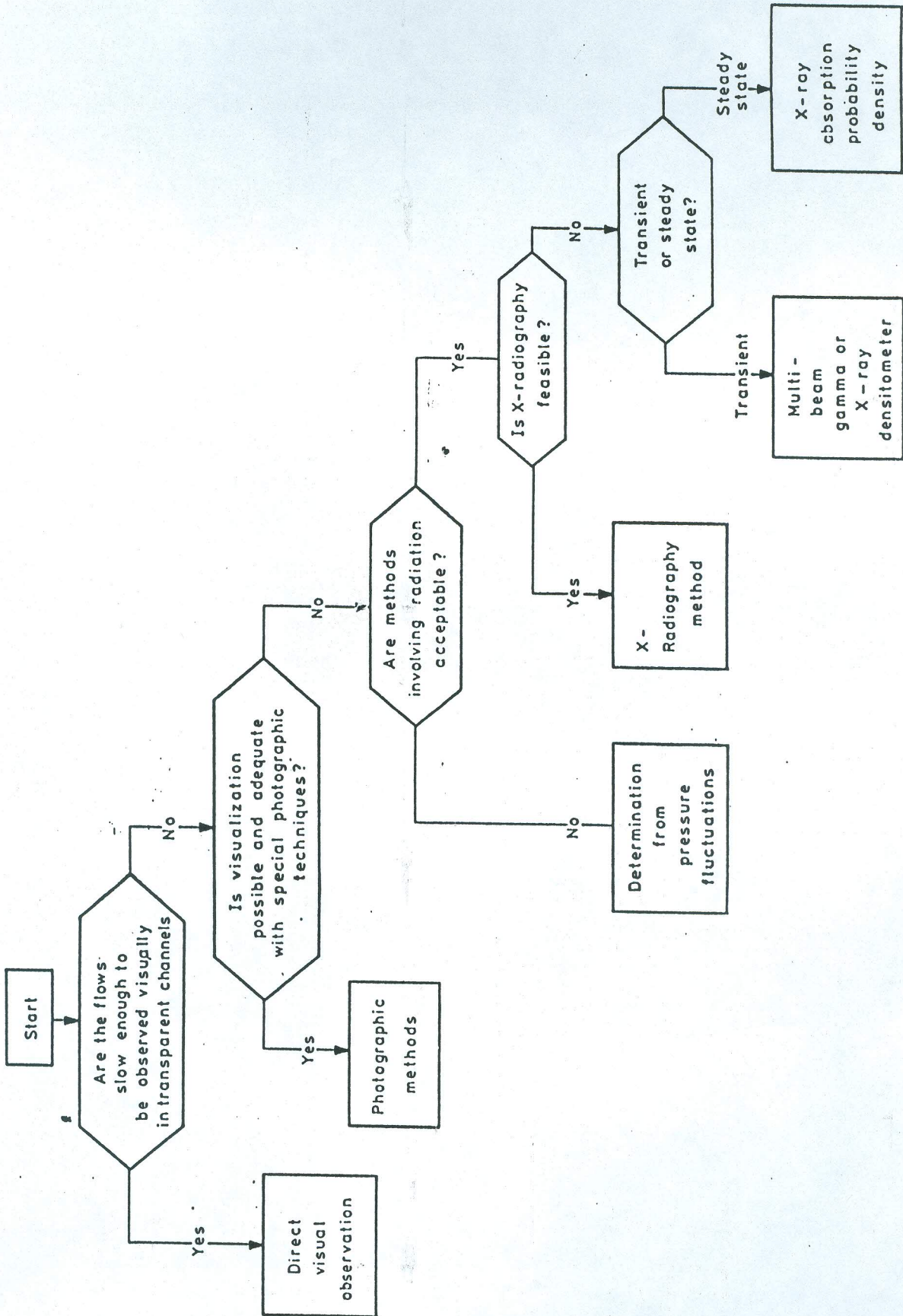
$$\frac{dP_g}{dz} = -g[(1-a)\rho_L + a\rho_G]$$

ΥΠΟΛΟΓΙΣΜΟΣ ΤΗΣ ΠΤΩΣΗΣ ΠΙΕΣΗΣ ΛΟΓΩ ΕΠΙΤΑΧΥΝΣΗΣ

$$\frac{dP_a}{dz} = -\rho_H^2 \frac{d(1/\rho_H)}{dz}$$

$$\frac{1}{\rho_H} = \frac{x}{\rho_G} + \frac{1-x}{\rho_L}$$

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