

Subject	ΤΥΠΟΛΟΓΙΟ ΜΗΧΑΝΙΚΗ ΡΕΥΣΤΩΝ II	Date	Project
		Author	Report

ΔΥΝΑΜΙΚΗ ΡΟΗ

Η εξίσωση δυναμικού ταχύτητας

$$\vec{w} = \text{grad } \phi$$

μέ συνιστώσες

$$u = \frac{\partial \phi}{\partial x}, \quad v = \frac{\partial \phi}{\partial y} \quad \text{και} \quad w = \frac{\partial \phi}{\partial z}$$

Η ροϊκή συνάρτηση $u = \frac{\partial \psi}{\partial y}, \quad v = -\frac{\partial \psi}{\partial x}$

Ροϊκή συνάρτηση

$$w_r = \frac{1}{r} \frac{\partial \psi}{\partial \theta}$$

$$w_\theta = -\frac{\partial \psi}{\partial r}$$

άστρόβιλη ροή

$$\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} = 0$$

$$\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} = 0$$

$$\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} = 0$$

L a p l a c e $\text{div } \vec{w} = \text{div} (\text{grad } \phi) = 0$

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$$

ΟΡΙΑΚΟ ΣΤΡΩΜΑ

Λύση Blasius

πάχος οριακού στρώματος	$\delta = \frac{4,92 x}{\sqrt{Re_x}} = \frac{5x}{\sqrt{Re_x}}$
Τοπικός συντελεστής αντίστασης	$c_f = \frac{\tau_o}{\rho u_\infty^2 / 2} = \frac{0,664}{\sqrt{Re_x}}$
Διατμητική τάση	$\tau_o(x) = 0,332 \mu u_\infty \frac{\sqrt{Re_x}}{x}$
Ολικός συντελεστής αντίστασης και για τις δυο πλευρές	$c_f = \frac{2D}{\rho u_\infty^2 / 2} = \frac{1,328}{\sqrt{Re_L}}$
Αντίσταση της μιας πλευράς	$D = 0,664 \sqrt{u_\infty^3 \mu \rho L} b$
Πάχος μετάθεσης	$\delta_1 = \frac{1,7208 x}{\sqrt{Re_x}}$
Πάχος απώλειας ορμής	$\delta_2 = \frac{0,664 x}{\sqrt{Re_x}}$

Λύση Pohlhausen

$\delta = \sqrt{\frac{2\beta_1}{\alpha_1}} \frac{x}{\sqrt{Re_x}}$
$c_f = \frac{\tau_o(x)}{\rho u_\infty^2 / 2}$
$\tau_o(x) = \sqrt{\frac{\alpha_1 \beta_1}{2}} \mu \frac{u_\infty}{x} \sqrt{Re_x}$
$D = b \sqrt{2\alpha_1 \beta_1} \sqrt{\mu \rho L u_\infty^3}$
$\delta_1 = \alpha_2 \delta$
$\delta_2 = \alpha_1 \delta$

όπου:

$$\alpha_1 = \int_0^1 f(\eta) (1 - f(\eta)) d\eta$$

$$\alpha_2 = \int_0^1 (1 - f(\eta)) d\eta$$

$$\beta_1 = f'(\eta) |_{\eta=0}$$

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ΕΞΙΣΩΣΕΙΣ ΣΥΝΕΧΕΙΑΣ ΚΑΙ ΟΡΜΗΣ (Navier-Stokes)

Καρτεσιανές
Συντεταγμένες

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x}(\rho v_x) + \frac{\partial}{\partial y}(\rho v_y) + \frac{\partial}{\partial z}(\rho v_z) = 0$$

$$X: \rho \left(\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) = - \frac{\partial p}{\partial x} + \mu \left(\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right) + \rho g_x$$

$$Y: \rho \left(\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) = - \frac{\partial p}{\partial y} + \mu \left(\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2} \right) + \rho g_y$$

$$Z: \rho \left(\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) = - \frac{\partial p}{\partial z} + \mu \left(\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2} \right) + \rho g_z$$

Κυλινδρικές
Συντεταγμένες

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r}(\rho r v_r) + \frac{1}{r} \frac{\partial}{\partial \theta}(\rho v_\theta) + \frac{\partial}{\partial z}(\rho v_z) = 0$$

$$r: \rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) = - \frac{\partial p}{\partial r} + \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r}(r v_r) \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right] + \rho g_r$$

$$\theta: \rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right) = - \frac{1}{r} \frac{\partial p}{\partial \theta} + \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r}(r v_\theta) \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right] + \rho g_\theta$$

$$z: \rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) = - \frac{\partial p}{\partial z} + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] + \rho g_z$$

Νόμος τριβής
Newton
 $\tau = \mu \frac{du}{dy}$

ΔΥΝΑΜΕΙΣ ΣΕ ΣΩΜΑΤΑ

άνωση

άντισταση

στατική

- άνωση

$$L = c_L A \rho u_\infty^2 = c_L A \frac{\rho u_\infty^2}{2}$$

$$D = c_D A \frac{\rho u_\infty^2}{2}$$

$$F_A = \int_V \rho g dV = \rho g V$$