## Managing Big Data Regression

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 Investigate and quantify the relationship between variables in a dataset using an existing dataset.

- In particular, investigate the effects of one (or more) variable(s) of the dataset onto the value of another variable in the dataset.
  - How does the value of one variable change if other variable(s) change value?

 Goal: come up with a model (i.e. a function) that predicts and explains the value of one variable based on the values of other variables.

- In regression, the relationship expressed is between one variable -called the dependent variable- and one or more independent variables
- Important! In regression, dependent variable takes continuous values
  - > Independent variables can be of any type
- Relationship between variables take the form of a function/equation: Aims at expressing the value of the dependent variable as a function of the values of other independent variables.
  - Function also referred to as "regression model", "regression equation" or plain "regression".

- Regression equations can take many different forms
  - > But does not
- Examples of regression equations/models
  - > FoodConsumption = 0.78 Income + 1459
    - e.g. for quantifying the relationship between annual FoodConsumption (dependent variable) of families and their annual income (independent)
  - > CarValue = PurchaseValue e<sup>(0.88\*age) e.g.</sup>
    - E.g for quantifying the relationship between the present value of a car (dependent variable) and the variables purchase value and age (independent variables).

• Purpose of regression models

- Explain the variance in the dependent variable based on the values of the independent variables(s) of the existing dataset
- Predict the value of the dependent variable based on the values of the independent variable(s)

- Regression analysis requires a training set with observations on these variables from which the relationship between the interested variables will be quantified.
- A regression model tries to come up with an equation that <u>best</u> "fits" the training set.
  - There can be many regression equations that fit the data, but we require the one that fit the best
  - This "fit" can assessed and the usefulness of the model can be determined.

### Terminology

Independent variables/Predictors/Regressors

#### $varY = b_1 varX_1 + b_2 varX_2 + b_3 varX_3 + ... + b_0$

Dependent variable Coefficients/ parameters

Intercept/bias

- In a regression model, the unknowns are the coefficients which must be estimated from the training set
  - Estimation of coefficients is done using the existing training dataset
  - Values of the independent variables are not unknowns-known from the training set

#### • Types of regression models

- > Based on how the value of the dependent variable changes when the values of the independent variables or coefficients change (That's very, very important and always to keep in mind – determines the form of the regression model)
  - i.e. how a change in the coefficients/parameters and independent variables affect the dependent variable.
  - Expressed as rate of change:  $\frac{\Delta Y}{\Delta X}$ ,  $\frac{\Delta Y}{\Delta h}$
- > Two types
  - Linear regression models
  - Nonlinear regression models

#### Types of regression models

- > Linear regression models
  - In linear regression models the dependent variable <u>depends linearly</u> on all the coefficients/parameters (and only the coefficients!)
  - "Depends linearly" means that the rate of change of the dependent variable -if the coefficient changes- is independent of the value of the coefficient (i.e. constant wrt coefficient).
  - Linear regression models do not need to depend linearly on the independent variables!

#### Types of regression models

- > Linear regression models
  - The model Consumption = b<sub>1</sub>Income + b<sub>0</sub> is a linear model because the value of consumption depends linearly on all coefficients b of the model: (e.g. assuming coefficient b<sub>1</sub> increases by 1):



#### Types of regression models

- > Linear regression models
  - Dependent variable does not need to be linear on the independent variables (can be but not is not required). This means linear regression models – when plotted- can form curves.
  - This means that all the following regression models are also linear although they are not linear with respect to the variables.

 $Consumption = b_1 Income + b_2 Familty Size^3 + b_0$ 

These are considered linear models because you may substitute FamilySize<sup>3</sup> with a new variable say Z  $BloodPresure = b_1Sex + b_2\sqrt{Age} + b_0$ 

 $ln (Income) = b_1 Experience + b_2 Experience^2 + b_3 Years Education + b_0$ 

#### Types of regression models

- > Nonlinear regression models
  - In nonlinear regression models the dependent variable does <u>not depend linearly</u> on all the coefficients (and only the coefficients!)
  - "Does not depend linearly" means that the rate of change of the dependent variable -if one of the coefficient changes- is dependent of the value of the coefficient.

## Types of regression models Nonlinear regression models

 The following examples are nonlinear regression models

Rate of reaction =  $\frac{b_1 Concentration}{b_2 + Concentration}$ 

Rate of a chemical reaction and the concentration of substance

Crop yield =  $\frac{1}{(b_1 + b_2 Crop Spacing)^{b_3}}$ 

#### The notion of error in regression models

- Regression model are approximations that try to fit in the best way possible the real values of the dependent variable in the training set.
  - Because regression models approximate the value of the dependent variable, they never succeed in predicting the real value of the dependent variable.
    - But what is the real value of the dependent variable?

The notion of error in regression models

- > Two types of errors in regression models
  - Errors/disturbance
    - The difference between the (unobserved) real value of the dependent variable in the population and the observed value in the training set. This error can never be observed or measured because we are unaware of the real value of the dependent variable in the population.
  - Residuals/fitting deviations
    - The difference between the dependent value in the training set and the predicted/estimated value by the regression model. This can be observed and measured

The notion of error in regression models

- Errors and residuals are included in the regression models.
  - Adding term  $\epsilon$  (for error) when showing the general model or  $\epsilon_i$  (for residuals) when
- Full specification of a regression model includes error term e.g.

Consumption =  $b_1$ Income +  $b_2$ FamiltySize<sup>3</sup> +  $b_0$  +  $\varepsilon$ 

- If the error term is not explicitly included in the regression model, it's implied.
  - This means, there always is an error term!

#### More types of regression models

- Simple regression models
  - When the regression model includes only 2 variables: one dependent and one independent variable
    - E.g. Income =  $b_1$ Education +  $b_0$
- Multiple regression models
  - When the regression model includes more than 2 variables
    - E.g. Income =  $b_1$ Education +  $b_2$ Experience +  $b_0$

- Who comes up with regression models and how?
  - Domain experts (economist, statisticians, engineers, etc)
    - Theory
      - Read the relevant literature and identify factors that affect the value of the dependent variable
    - Look at the data and how it changes
      - From existing data, see how the dependent variable changes when the independent variables change
    - Trial and error
      - Begin by trying simple regression models and assess the results. Continue by modifying the model if results are not appropriate.

Who comes up with regression models?

> Don't forget: Regression models are approximations that try to fit the best way possible the data in the training set.

Estimating parameters in regression models

- In a regression model, the problem is estimating the coefficients/parameters that will indicate the relationships between the variables
  - Coefficients/parameters are estimated from an existing dataset (training set) which is required.

	Tid	House Price	Marital Status	Income	m <sup>2</sup> House
ing	1	190K	Single	125K	180
	2	145K	Married	100K	154
	3	101K	Single	70K	110
	4	187K	Married	120K	167
	5	109K	Divorced	95K	110
	6	96K	Married	60K	90
	7	200K	Divorced	220K	190

Train

set.

#### Income = $b_1 m^2 House + b_0$

Unknowns are the parameters b (independent variables known from training set). The parameters b of this regression model are estimated using the training set. The goal: find the best values of b which best fit the values of the dependent variable in the training set.

- Different methods to estimate parameters based on the type of the regression model
  - > Linear vs Nonlinear

 The general idea: Estimation of parameters in regression model (linear or nonlinear) involves a Cost function (also called "Loss function") that needs to be minimized.

- Cost function tries to measure how big the error of the regression model is when estimating the value of the dependent variable
  - Essentially, this is the sum of residuals which is to be minimized
  - Cost functions can have many different forms
    - Depending on the purpose
    - The form of the cost function determines the type of regression: Ordinary Least Squares (OLS), LASSO, Quantile etc

Estimating parameters in linear regression models

Estimating parameters
Linear regression models have the following general form:

#### $Y = b_1 X_1 + b_2 X_2 + b_3 X_3 + \cdots + b_k X_k + b_0 + \varepsilon$

Where: Y: Dependent variable X<sub>1</sub> : Independent variable i b<sub>1</sub>: Parameter to be estimated ɛ: Error term Estimating parameters
Since linear regression models try to fit the available training data, the linear regression model can also be written in the form:

 $Y_i = b_1 X_{1i} + b_2 X_{2i} + b_3 X_{3i} + \dots + b_k X_{ki} + b_0 + e_i$ 

#### Where:

Y<sub>i</sub>: Value of dependent variable in observation i in training set X<sub>ki</sub>: Value of independent variable k in observation i of the training set b<sub>i</sub>: Parameter to be estimated e<sub>i</sub>: Residual of the i-th observation in the training set Estimating parameters
If there are n observations in the training set, then there will be n equations, one for each observation, of the form:

 $Y_i = b_1 X_{1i} + b_2 X_{2i} + b_3 X_{3i} + \dots + b_k X_{ki} + b_0 + e_i$ 

 Because parameters are estimated from the training set and not the truly real values of the variables (remember: the training set is just a sample), the estimates are mentioned in the regression model

## $\widehat{Y}_i = \widehat{b}_1 X_{1i} + \widehat{b}_2 X_{2i} + \widehat{b}_3 X_{3i} + \dots + \widehat{b}_k X_{ki} + \widehat{b}_0 + e_i$

#### Where:

 $\hat{Y}_i$ : The estimated value of the dependent variable  $\hat{b}_i$ : The estimated value of the parameter i.

# Estimating parameters Regression model in matrix notation It's customary to represent these n regression equation in matrix notation. If we define:



Then the n linear regression equations, derived from the training set, can be written in matrix form:

$$\widehat{Y} = X\widehat{b} + e$$

If you carry out the operations, you'll get the n linear regression equations as vectors. The matrix form makes it easier to calculate the parameters.

- Two methods for estimating the parameters of linear regression models
  - > Ordinary Least Squares (OLS)
  - > Gradient Descent and its variations
- Each of the above method appropriate in specific situations.



 Estimating parameters
Ordinary Least Square (OLS) Regression
In OLS the cost function is the Sum of Squared Errors (SSE) i.e. sum of residuals which must be minimized:

$$SSE = \sum_{i=1}^{n} e_i^2 = \sum_{i=1}^{n} (Y_i - \widehat{Y}_i)^2$$

 $Y_i$  = Value of the dependent variable in observation i of the training set  $\hat{Y}_i$  = Estimated value by the linear regression model for the values of the independent variables in observation i in the training set.

The parameters b which minimize the above SSE are the parameter estimates of the linear regression model that best fit the training data.

- Ordinary Least Square (OLS) Regression
  - > How is the Cost function (SSE) minimized in OLS?
  - First write SSE in matrix notation as a function of the vector b

$$SSE(\widehat{b}) = e^T e = (Y - X\widehat{b})^T (Y - X\widehat{b})$$

> And then minimize the Cost function (SSE) by solving the equation of partial derivatives:



This equation has a closed form solution due to the form of the linear regression. Solving this will calculate the vector b that minimizes the SSE and hence finds the parameters we are looking for.

Ordinary Least Square (OLS) Regression

The closed form solution derived from the previous equation for estimating the parameters b of a linear regression model in matrix form is:

 $\widehat{\boldsymbol{b}} = \left(\boldsymbol{X}^T \boldsymbol{X}\right)^{-1} \boldsymbol{X}^T \boldsymbol{Y}$ 

The above closed form formula – <u>called normal</u> <u>equation</u> - gives you the vector of parameters estimates b, based on the matrix of values of the independent variables X and the matrix of the values of the dependent variable Y in the training set, which minimize SSE and hence what we were looking for.

## **Gradient descent**
- Gradient descent
  - > While OLS minimizes the SSE in a very specific way (by finding the values of b who yield the partial derivative to zero) leading to a closed form formula (the normal equation) for estimating the parameters, Gradient descent minimizes the cost function in a very different way.
  - Gradient descent is an <u>iterative, numerical</u> <u>optimization method</u> for minimizing the cost function and thus finding the parameter estimates.
    - i.e. Gadient descent does not offer a closed form formula like the normal equation in OLS for calculating the parameters.
    - "iterative" ? Tries to guess the proper values of the parameters that lead to minimizing the cost function

- Gradient descent
  - > Why Gradient descent?
    - OLS has one big concern: The normal equation requires inversion of a matrix:

$$\widehat{b} = (X^T X)^{-1} X^T Y$$

Matrix inversion is a very expensive operation. If the X<sup>T</sup>X matrix has 100 variables (is an 100x100 matrix), since an inversion requires n<sup>3</sup> operations (n=dimension of matrix) on average, it would require ~1000000 operations to invert the matrix.
 OLS not suitable for big data!

- Gradient descent
  - > Why Gradient descent?
    - Gradient descent performs much better –in terms of execution times/number of operations- in big data contexts than OLS and in such situations it's exclusively used.

 There are even versions that increase the performance of the algorithm

 Warning! Gradient descent uses a different notation for the multiple linear regression model:

$$h_{\theta}(x^{(i)}) = \theta_1 x_1^{(i)} + \theta_2 x_2^{(i)} + \dots + \theta_k x_k^{(i)} + \theta_0 + \varepsilon$$

 $\theta_i$  = Parameter j (to be estimated)

Solution i in training set

Estimating parameters
 Cost function in Gradient descent
 In Gradient descent the cost function is called the mean squared error, J(0)

$$J(\theta_0, \theta_1, \dots, \theta_{\kappa}) = \frac{1}{2m} \sum_{i=1}^m \left(h_\theta(x^{(i)}) - y^{(i)}\right)^2$$

#### Where:

 $\theta_i$  = (Unknown) parameter i of the linear regression model from a total of k+1 parameters m = Number of observation in training set  $h_{\theta}$ () = The estimated value of the linear regression model for the values of the independent variables at observation i in training set.  $x^{(i)}$  = The values of the independent variables of observation i in training set  $y^{(i)}$  = The value of the dependent variable of observation i in training set

### Estimating parameters Cost function in Gradient descent

 Gradient descent attempts to minimize the cost function J(θ) by finding/estimating the proper values of parameters θ.

$$J(\theta_0, \theta_1, \dots, \theta_{\kappa}) = \frac{1}{2m} \sum_{i=1}^m \left( h_\theta(x^{(i)}) - y^{(i)} \right)^2$$

Often abbreviated simply as  $J(\theta)$ .

Estimating parameters
 Cost function in Gradient descent

 Cost function has things in common with the cost function (i.e. SSE) in OLS.

$$J(\theta_0, \theta_1, \dots, \theta_\kappa)$$

Why divide by 2m? m because of two reasons: i) it's the mean squared error and ii) it yields to smaller numbers which is important due to the numerical nature of the method. Also, include the constant 2 in denominator to make things simpler as it's shown later on (hint: it will be eliminated). However, these terms do not affect the minimization

process.

Sum of squared errors in OLS

 $\frac{1}{2m}\sum \left(h_{\theta}(x^{(i)})-y^{(i)}\right)^2$ 

Form of the linear regression model, with θ the unknown parameters, is:

$$h_{\theta}(x^{(i)}) = \theta_1 x_1^{(i)} + \theta_2 x_2^{(i)} + \dots + \theta_k x_k^{(i)} + \theta_0 + \varepsilon$$

Estimating parameters
 Cost function in Gradient descent
 Cost function in matrix form

$$J(\theta) = \frac{1}{2m} (X\theta - y)^T (X\theta - y) = \frac{1}{2m} (X\theta - y)^2$$

Where:

Vector of dependent variables

 $y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} X = \begin{bmatrix} 1 & X_{11} & X_{21} & \dots & X_{k1} \\ 1 & X_{12} & X_{22} & \dots & X_{k2} \\ 1 & X_{13} & X_{23} & \dots & X_{k3} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ 1 & X_{1n} & X_{2n} & \dots & X_{kn} \end{bmatrix} \theta = \begin{bmatrix} \widehat{\theta}_0 \\ \widehat{\theta}_1 \\ \widehat{\theta}_2 \\ \vdots \\ \widehat{\theta}_k \end{bmatrix}$ 

Sum of all elements to get pure number of  $J(\theta)$ .

element of vector

Vector of estimated parameters

Matrix of independent variables with first columns all 1s

### Cost function

- A note on notation: cost function in gradient descent uses different notation (θ instead of b for parameters, h<sub>θ</sub>() for linear regression model, J(θ) for cost function)
- > This is because Gradient descent originated from a different field. One of the first algorithms which founded the area of machine learning in applied mathematics
- > We use the same notation used by contemporary literature.

- General idea of estimating the parameters θ with Gradient descent which minimize the cost function J(θ)
  - Start with initial, random values for the parameters θ
  - > Update/Change the values of the parameters θ in a way that yield to smaller value of the cost function J(θ)
  - Continue changing values of θ iteratively until the smallest value of J(θ) is attained.



### The general idea of Gradient descent.

Assume a simple linear regression model  $h_{\theta}(x) = \theta_0 + \theta_1 x$ 

The cost function of such linear regression model,  $J(\theta)$ , will be convex and an example cost function is depicted on the left.

Gradient descent tries to modify the values of all the parameters  $\theta$  iteratively, towards the smallest value of J( $\theta$ ).

- How to change the values of parameters  $\theta$  in order to minimize  $J(\theta)$ ?
  - > The value of the first partial derivative of the cost function  $J(\theta)$  with respect to a parameter  $\theta_j$  will tell us **how we need to modify the parameter \theta\_j** (leaving all other parameters constant) to achieve a smaller value of  $J(\theta)$ .
- Remember from your math:
  - If the value of the first derivative of a function f(x) with respect to x is at some point x<sub>0</sub>
    - positive (>0), an increase of x<sub>0</sub> leads to an increase of f(x). A decrease of x<sub>0</sub> leads to decrease of f(x)
    - negative (<0), an increase of x<sub>0</sub> leads to an decrease of f(x). A decrease of x<sub>0</sub> leads to increase of f(x)
    - is equal to zero (=0), an increase of  $x_0$  leads to an increase or decrease of f(x) (has a point of deflection at  $x_0$ ).

- How to change the values of parameters θ in order to minimize J(θ)?
  - In essence, the value of the first derivative with respect to some x tells us if x needs to increase or decrease in order to achieve a smaller value of the function f(x).
    - Value of the first derivative tells us the direction of change of variable x (increase or decrease).

- How to change the values of parameters θ in order to minimize J(θ)?
  - J(θ) is a multivariate function, where the parameters θ<sub>i</sub> are the unknown variables.
  - > To apply the derivative technique, we will use the first partial derivative wrt to one  $\theta_j$  parameter and leaving other  $\theta_s$  constant i.e. calculate the value of  $\frac{\partial J(\theta)}{\partial \theta_j}$ . If this value is positive, a decrease of  $\theta_j$  will decrease the cost function, if it's negative, an increase of  $\theta_j$  will decrease the cost function J( $\theta$ ).
    - Do this for all parameters θ to see how they need to change i.e. calculate VJ(θ)
    - Do this iteratively to get an even smaller value J(θ)

- How to change the values of parameters  $\theta$  in order to minimize J( $\theta$ )?
  - > A more clear example
    - if initial parameters of  $\theta = (\theta_0, \theta_1, \theta_2, ..., \theta_k)$  and at that point the cost function is  $J(\theta)$ , then if the value of  $\frac{\partial J(\theta)}{\partial \theta_2}$  is negative, this means that **a small increase** (update/change) of parameter  $\theta_2$  leading to parameters  $\theta' = (\theta_0, \theta_1, \theta_2 + \varepsilon ..., \theta_k)$  (leaving all other  $\theta_3$  the same) will decrease  $J(\theta)$ . If it's positive, decrease  $\theta_2$  to get  $\theta' = (\theta_0, \theta_1, \theta_2 - \varepsilon ..., \theta_k)$ , to get a smaller  $J(\theta)$ .

• i.e.  $J(\Theta') < J(\Theta)$ 

- Do the same for each and all 0s in the linear regression model and update their values accordingly.
- Do such update for each θ iteratively (i.e. many times over).

- How to change the values of parameters θ in order to minimize J(θ)?
  - In Gradient descent, each parameter is updated/changed, at each iteration, using the following formula:

$$\theta_j \coloneqq \theta_j - \alpha \frac{\partial J(\theta)}{\partial \theta_j}$$

**a** is a real value > 0, called the learning rate. It is a constant given as input to gradient descent. While the partial derivative will give us the direction in which the cost function will decrease, it does not specify how big the increase of  $\theta$  should be. This is specified by the value of the learning rate a. Can be imagined as the step by which the  $\theta$  will change. Setting the appropriate value for a is very important and affects the significantly the algorithm.

- How to change the values of parameters  $\theta$  in order to minimize J( $\theta$ )?
  - > For a multiple linear regression model, you can actually calculate  $\frac{\partial J(\theta)}{\partial \theta}$  for all  $\theta$ s, resulting in the following update formulas for the parameters  $\theta$ :

#### Where

m: number of observations in training set

h<sub>0</sub>(x<sup>(i)</sup>) : value of linear regression model for the values of independent variables in observation i of the training set

y<sup>(i)</sup> : value of the dependent variable in observation i of the training set

•: learning rate

 $x_i^{(0)}$ : value of independent variable  $x_i$  in observation i of the training set

Form of linear regression model:  $h_{\theta}(x^{(i)}) = \theta_1 x_1^{(i)} + \theta_2 x_2^{(i)} + \dots + \theta_k x_k^{(i)} + \theta_0 + \varepsilon$ 

- How to change the values of parameters θ in order to minimize J(θ)?
  - In matrix form, the previous update formulas for parameters θ can be written as

$$\boldsymbol{\theta} := \boldsymbol{\theta} - \boldsymbol{\alpha} \frac{1}{m} \boldsymbol{X}^T \left( \boldsymbol{X} \boldsymbol{\theta} - \boldsymbol{Y} \right)$$

#### Where:

m: Number of observations in training set
i The vector of (k+1) parameters of the linear regression model
X: The mx(k+1) matrix of values of independent variables in the linear regression model, with the first column all 1 (ones).
Y: The vector of m values of the dependent variables in the training set
a: the learning rate, given as input

Estimating parameters
 Gradient descent algorithm
 > Pseudocode

Initialize vector of parameters  $\theta$  with random values Initialize costVector # We will store the value of the cost function for each iteration in this vector.

 $\alpha$  = 0.01 # Set learning rate. See later how to come up with an appropriate value.

# Start iterations of Gradient descent
while termination conditions not met {

update  $\theta$  vector with  $\theta := \theta - \alpha \frac{1}{m} X^T (X \theta - Y)$ calculate value of cost function J( $\theta$ ) for the newly calculated values of  $\theta$ Store value of cost function into vector costVector

# Vector  $\theta$  will contain the estimated parameters which minimize  $J(\theta)$ print  $\theta$  vector # Print the estimated parameters plot costVector # Plot the costVector Estimating parameters
 Gradient descent usually depicted as a contour plot



Convergence of  $\theta$ s to the values which minimize J( $\theta$ ) is usually depicted as Contour plot.

In a Contour plot, each circle represents the values of  $\theta$  that lead to the same value of J( $\theta$ ).

- When does Gradient descent terminate?
  - > 3 possible termination conditions
    - When a predefined number of iterations have been completed. Typical number of iterations are n=50, 20000 or greater depending how fast the algorithm converges
    - When the improvement of the cost function is smaller than a predefined value
    - Early stopping. With the current "version" of the cost function, calculate the cost on a validation set (different from training set) at each iteration. Compare the two consecutive values of  $J(\theta)$  and if  $J(\theta)$  starts to increase, terminate the algorithm. Used to address overfitting.

## Estimating parameters Gradient descent algorithm with predefined number of iterations as termination condition

```
Initialize vector of parameters \theta with random values
Initialize costVector # We will store the value of the cost function J(\theta) for each iteration
here
\alpha = 0.01 # Setting the learning rate
numIterations = 10000 # Number of iterations to carry out
n = 0 # How many iterations we have done
while n < numIterations {</pre>
      update \theta vector with \theta := \theta - \alpha \frac{1}{m} X^T (X \theta - Y)
       calculate value of cost function J(\theta) for the newly estimated values of \theta
       Store value of cost function into vector costVector
       n = n + 1 # Next iteration
# Vector \theta will contain the estimated parameters which minimize J(\theta)
print \theta vector
plot costVector
```

- The learning rate a
  - Setting the learning rate a to the proper value is critical!
    - Determines if and how fast Gradient descent converges to the minimum of the cost function.
    - If the value of the learning parameter is too small, Gradient descent may converge very slowly
    - If the value of the learning parameter is too large, Gradient descent may not converge at all to the proper values of θ which minimize J(θ)
  - How to check if learning parameter a is too small, too big or just appropriate?
    - Empirically, plot the cost function and see its shape

## Estimating parameters The learning rate a Appropriate value of learning rate



(l) (B)

If the value of the learning rate is appropriate, the cost function J(θ) plotted against the number of iterations will have such shape. Cost function shows a steep drop and then a gradual improvement.

To check if the selected value is appropriate, run Gradient descent and plot the cost function.

### Estimating parameters • The learning rate a

> Too small value of the learning rate a



If the value of the learning rate is too small, the cost function  $J(\theta)$  plotted against the number of iterations will have such shape.

This means Gradient descent will converge very, very slowly to the appropriate values of  $\theta$ s that minimize  $J(\theta)$ .

## Estimating parameters The learning rate a Too big value of the learning rate a



If the value of the learning rate is too big, the cost function J(θ) plotted against the number of iterations will have such a shape. The cost function increases with each iteration.

# Estimating parameters The learning rate a Too big value of the learning rate a



If the value of the learning rate a is too big, Gradient descent may overshoot the proper values of  $\theta$  that minimize the cost function.

Overshooting happens because the value of a is too big and hence the update  $\theta_j$ =  $\theta_j - a \frac{\partial J(\theta)}{\partial j}$  the new values of  $\theta_j$  may increase by too much, missing the values for which J( $\theta$ ) is minimized. Gradient descent then diverges from the proper values of  $\theta_s$ .

- The learning rate a
  - > Appropriate values for learning rate?
    - Typical values of the learning rate a are 0.001, 0.01, 0.1
    - Execute Gradient descent with such values of the learning rate a and plot the cost function J(θ) as a function of the number of iterations. Compare the shape of the plot with the plots shown previously.
    - If learning rate is too small, increase it by some amount e.g. from 0.01 to 0.03. Execute Gradient descent again and plot the cost function. Stop if the plot of the cost function has the appropriate shape.

- The version of Gradient descent discussed previously is the "plain vanilla" style of the algorithm also known as "Batch Gradient Descent"
- Two other versions of Gradient Descent available that improve performance dramatically in Big data settings:
  - > Stochastic gradient descent SGD
  - Mini-Batch gradient descent MBGD

- Why the need to improve the performance of Gradient descent?
  - If number of observations in training set is large (e.g. 1000000 observations/records or more), there are two main concerns with Batch Gradient descent:
    - Entire training set must be stored into memory (RAM)
    - Update formulas must iterate over the entire training set to calculate on step for all parameters in each iteration.
    - In such settings, Batch Gradient descent is computationally expensive!

 Concern: Entire training set into memory
 Looking at the matrix form of the update formula: Does is fit into memory?

 $\boldsymbol{\theta} := \boldsymbol{\theta} - \boldsymbol{\alpha} \frac{1}{m} \boldsymbol{X}^T \left( \boldsymbol{X} \boldsymbol{\theta} - \boldsymbol{Y} \right)$ 

To execute this calculation, the entire matrix of the values of the independent variables X must be loaded into the main memory (RAM). What if it does not fit into RAM? E.g. if there are 10000000 observations and 50 numeric variables, you'll need to store 10000000 \* 50 = 500000000 numbers and since each number requires at least 4 bytes you need 500000000 \* 4= 2000000000 bytes of data in RAM or ~1.8GB of RAM. Do you have it?

- Concern: Iterate over the entire training set at each iteration
  - > Looking at the analytic formula indicates better the problem (Note: the same argument holds for the matrix form, but it's clearer in the analytic form of the update formula): Can be slow in big data contexts

If the training set has m=10000000 observations, we iterate over all 10000000 observations just make one (1) update to one (1) parameter at one (1) iteration! Considering that we have many parameters, we traverse the 10000000 observations many times at each iteration. This makes Batch Gradient descent slow.

$$heta_j := heta_j - lpha \ rac{1}{m} \sum_{i=1}^m ig(h_{ heta}(x^{(i)}) - y^{(i)}ig) x_j^{(i)}$$

- Why the need to improve the performance of Gradient descent?
  - The solution in such big data environments is simply not to iterate over the entire training set at each iteration!
  - The two other versions of Bath Gradient descent treat/scan the training set differently

Stochastic Gradient Descent - SGD

At each iteration, SGD uses only one observation of the training set to update the parameters (instead of the entire training set in GD)

```
Initialize all parameters \theta_i with random values
Initialize costVector # We will store the value of the cost function J(\theta) for each iteration here
\alpha = 0.01 \# Setting the learning rate
Randomly shuffle the training set # To ensure that the observations do not have some kind of order
while termination criteria not met{
      Calculate cost function and store its value in costVector
      for each observation i in training set {
        for each parameter \theta_{i} {
             Set new value of parameter new_{	heta_j} \coloneqq 	heta_j - lpha\left(h_	heta(x^{(i)}) - y^{(i)}
ight) x_j^{(i)}
       calculate value of cost function J(\theta) for the newly estimated values of \theta
       Store value of cost function into vector costVector
      \theta_{i} := new<sub>\Theta_{i}</sub>
      n = n + 1 # Next iteration
# Vector \theta will contain the estimated parameters which minimize J(\theta)
plot costVector
```

### Pros/Cons of SGD

> Pros

- It's a so-called online algorithm you see the update of parameters immediately, in a sequential fashion, during their estimation i.e. in real time. That's not possible with Batch GD
- Does not require entire training set in memory
- Avoids local minima of J(θ)
- > Cons
  - Can be noisy i.e. parameters jump around at each epoch with greater variance between epochs (epoch = one update of all parameters)

- Mini-Batch Gradient Descent MBGD
  - > MBGD does not use one single observation of the training set to update the parameters. It uses a "small batch" of training set observations – typically between 2 and 100 observation in each batch.
    - To do this, we cut the large training set into smaller training subsets, and use these to update the parameters at each step
    - It's a method "between" the extremes of Batch Gradient descent (which uses entire training set for each parameter update) and Stochastic Gradient descent which uses only one observation to update the parameters.

### Mini-Batch Gradient descent

```
Initialize all parameters \theta_i with random values
Initialize costVector # We will store the value of the cost function J(\theta) for each iteration here
\alpha = 0.01 \# Setting the learning rate
Randomly shuffle the training set # To ensure that the observations do not have some kind of order
Cut the training set into batches/subsets b_i each of size n_b such that b_i * n_b = m \# Note: last batch
might be smaller than n<sub>b</sub>
while termination criteria not met{
      Calculate cost function and store its value in costVector
      for each batch b; {
        for each parameter \theta_{i} {
             Set new value of parameter new_{	heta\,j} \coloneqq 	heta_j - lpha\,\sum_{\iota=1}^{n_b} ig(h_	heta(x^{(\iota)}) - y^{(\iota)}ig)\,x_j^{(\iota)}
       calculate value of cost function J(\theta) for the newly estimated values of \theta
       Store value of cost function into vector costVector
      \theta_i := new_{\Theta_i} \# update all parameters with new values
      n = n + 1 # Next iteration
# Vector \theta will contain the estimated parameters which minimize J(\theta)
print print \theta_{i}
plot costVector
```
## OLS vs Gradient descent

OLS	Gradient descent
Estimates the <b>same</b> , <b>unbiased parameters</b> for the same training set if the linear regression assumptions hold (No or little multicollinearity, No of auto-correlation of residuals, Homoscedasticity etc)	Estimates of <b>parameters are</b> approximations and biased. May result in different parameter estimates for the same training set and regression model.
Computationally <b>expensive in big data contexts</b> .	Suitable in big data contexts where number of variables and number of observation are very large
Can be used to estimate parameters <b>only for</b> <b>linear regression models</b>	Can be used (and is used) to estimate parameters in nonlinear regression models.
Offers <b>closed formulas (the normal equation)</b> for calculating the parameters	Does <b>not offer closed formula</b> . Parameter estimates are iteratively calculated
Requires entire training set in RAM	Versions of Gradient descent <b>do not require entire</b> <b>training set in RAM</b> (e.g. Stochastic Gradient descent)
Belongs to the field of linear algebra	Belongs to the field of machine learning
Taught and used mainly in social sciences	Taught and used mainly in computer science and engineering

## Appendices

Deriving update formulas for parameters in linear regression models

 We will derive as an example the update for parameter θ<sub>1</sub> (parameter for an independent variable) - the same analysis holds for all other parameters

$$\frac{\partial J(\theta)}{\partial \theta_{1}} = \frac{\partial \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^{2}}{\partial \theta_{1}} = \frac{\frac{1}{2m} \partial \sum_{i=1}^{m} (h_{\theta}(x^{(i)})^{2} - 2h_{\theta}(x^{(i)})y^{(i)} + y^{(i)^{2}})}{\partial \theta_{1}}$$
$$= \frac{1}{2m} \left[ \frac{\partial \sum_{i=1}^{m} h_{\theta}(x^{(i)})^{2}}{\partial \theta_{1}} - 2\frac{\partial \sum_{i=1}^{\mu} h_{\theta}(x^{(i)})y^{(i)}}{\partial \theta_{1}} + \frac{\partial \sum_{i=1}^{\mu} y^{(i)^{2}}}{\partial \theta_{1}} \right] = < \text{see next slide} >$$

Deriving update formulas for parameters in linear regression models

$$= \frac{1}{2m} \left[ \frac{\partial \sum_{i=1}^{m} h_{\theta}(x^{(i)})^{2}}{\partial \theta_{1}} - 2 \frac{\partial \sum_{i=1}^{\mu} h_{\theta}(x^{(i)}) y^{(i)}}{\partial \theta_{1}} \right]$$
  
$$= \frac{1}{2m} \left[ 2 \sum_{i=1}^{m} h_{\theta}(x^{(i)}) \frac{\partial h_{\theta}(x^{(i)})}{\partial \theta_{1}} - 2 \frac{\partial \sum_{i=1}^{\mu} h_{\theta}(x^{(i)}) y^{(i)}}{\partial \theta_{1}} \right]$$
  
$$= \frac{1}{2m} \left[ 2 \sum_{i=1}^{m} h_{\theta}(x^{(i)}) x_{1}^{(i)} - 2 \sum_{i=1}^{m} x_{1}^{(i)} y^{(i)} \right] = \frac{1}{m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)}) x_{1}^{(i)}$$

## Thus the update formula for parameter θ1 becomes

$$\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_1^{(i)}$$

Now do the same for all other parameters  $\theta 0$ ,  $\theta 2$ ,  $\theta 3$ ,.... and from this we get the closed form formulas for the updates of all parameters  $\theta$ .