The Probabilistic Method - Probabilistic Techniques

Lecture 9: "Markov Chains"

Sotiris Nikoletseas Professor

Computer Engineering and Informatics Department 2017 - 2018

Markov Chains - Stochastic Processes

- Stochastic Process: A set of random variables $\{X_t, t \in T\}$ defined on a set D, where:
 - T: a set of indices representing <u>time</u>
 - X_t : the <u>state</u> of the process at time t
 - D: the set of states
- The process is <u>discrete/continuous</u> when D is discrete/continuous. It is a <u>discrete/continuous</u> time process depending on whether T is discrete or continuous.
- In other words, a stochastic process abstracts a <u>random</u> phenomenon (or experiment) evolving with time, such as:
 - the number of certain events that have occurred (discrete)
 - the temperature in some place (continuous)

Markov Chains - transition matrix

• Let S a state space (finite or countable). A Markov Chain (MC) is at any given time at one of the states. Say it is currently at state i; with probability P_{ij} it moves to the state j. So:

$$0 \le P_{ij} \le 1$$
 and $\sum_{j} P_{ij} = 1$

The matrix $P = \{P_{ij}\}_{ij}$ is the <u>transition probabilities</u> matrix.

• The MC starts at an <u>initial state</u> X_0 , and at each point in time it moves to a new state (including the current one) according to the transition matrix P. The resulting sequence of states $\{X_t\}$ is called the history of the MC.

- Clearly, the MC is a <u>stochastic process</u>, i.e. <u>a random</u> process in time.
- the defining property of a MC is its memorylessness, i.e. the random process <u>"forgets" its past</u> (or "history"), while its "future" (next state) only depends on the "present" (its current state). Formally:

 $\Pr\{X_{t+1} = j | X_0 = i_0, X_1 = i_1, \dots, X_{t-1} = i_{t-1}, X_t = i\} = \Pr\{X_{t+1} = j | X_t = i\} = P_{ij}$

The initial state of the MC can be arbitrary.

t-step transitions

• For states $i, j \in S$, the <u>t-step transition probability</u> from i to j is:

$$P_{ij}^{(t)} = \Pr\{X_t = j | X_0 = i\}$$

i.e. we compute the (i, j)-entry of the <u>t-th power</u> of transition matrix P.

Chapman - Kolmogorov equations:

$$P_{ij}^{(t)} = \sum_{i_{1}, i_{2}, \dots, i_{t-1} \in S} \Pr\{X_{t} = j, \bigcap_{k=1}^{t-1} X_{k} = i_{k} | X_{0} = i\}$$
$$= \sum_{i_{1}, i_{2}, \dots, i_{t-1} \in S} P_{ii_{1}} P_{i_{1}i_{2}} \cdots P_{i_{t-1}j}$$

First visits

The probability of <u>first visit</u> at state j after t steps, starting from state i, is:

$$r_{ij}^{(t)} = \Pr\{X_t = j, X_1 \neq j, X_2 \neq j, \dots, X_{t-1} \neq j | X_0 = i\}$$

• The <u>expected number of steps</u> to arrive for the first time at state *j* starting from *i* is:

$$h_{ij} = \sum_{t>0} t \cdot r_{ij}^{(t)}$$

Visits/State categories

The probability of <u>a visit</u> (not necessarily for the first time) at state j, starting from state i, is:

$$f_{ij} = \sum_{t>0} r_{ij}^{(t)}$$

- Clearly, if $f_{ij} < 1$ then there is a positive probability that the MC never arrives at state j, so in this case $h_{ij} = \infty$.
- A state *i* for which $\underline{f_{ii}} < 1$ (i.e. the chain has positive probability of never visiting state *i* again) is a <u>transient state</u>. If $f_{ii} = 1$ then the state is <u>persistent</u> (also called <u>recurrent</u>).
- If state *i* is persistent but $h_{ii} = \infty$ it is <u>null persistent</u>. If it is persistent and $h_{ii} \neq \infty$ it is non null persistent.

Note. In <u>finite</u> Markov Chains, there are no null persistent states.



A Markov Chain



• The transition matrix P:

$$P = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} & 0 & 0\\ \frac{1}{2} & \frac{1}{8} & \frac{1}{4} & \frac{1}{8}\\ 0 & 0 & 1 & 0\\ 0 & 0 & 0 & 1 \end{bmatrix}$$

• The probability of starting from v_1 , moving to v_2 , staying there for 1 time step and then moving back to v_1 is: $\Pr\{X_3 = v_1, X_2 = v_2, X_1 = v_2 | X_0 = v_1\} =$ $= P_{v_1v_2}P_{v_2v_2}P_{v_2v_1} = \frac{2}{3} \cdot \frac{1}{8} \cdot \frac{1}{2} = \frac{1}{24}$

Example (II)

- The probability of moving from v_1 to v_1 in 2 steps is: $P_{v_1v_1}^{(2)} = P_{v_1v_1} \cdot P_{v_1v_1} + P_{v_1v_2} \cdot P_{v_2v_1} = \frac{1}{3} \cdot \frac{1}{3} + \frac{2}{3} \cdot \frac{1}{2} = \frac{4}{9}$ Alternatively, we calculate P^2 and get the (1,1) entry.
- The first visit probability from v_1 to v_2 in 2 steps is: $r_{v_1v_2}^{(2)} = P_{v_1v_1}P_{v_1v_2} = \frac{1}{3} \cdot \frac{2}{3} = \frac{2}{9}$ while $r_{v_1v_2}^{(7)} = (P_{v_1v_1})^6 P_{v_1v_2} = (\frac{1}{3})^6 \cdot \frac{2}{3} = \frac{2}{3^7}$ and $r_{v_2v_1}^{(t)} = (P_{v_2v_2})^{t-1} P_{v_2v_1} = (\frac{1}{8})^{t-1} \cdot \frac{1}{2} = \frac{1}{2^{3t-2}}$ for $t \ge 1$ (since $r_{v_2v_1}^{(0)} = 0$)

Example (III)

The probability of (eventually) visiting state v₁ starting from v₂ is:

$$f_{v_2v_1} = \sum_{t \ge 1} \frac{1}{2^{3t-2}} = \frac{4}{7}$$

• The expected number of steps to move from v_1 to v_2 is:

$$h_{v_1v_2} = \sum_{t \ge 1} t \cdot r_{v_1v_2}^{(t)} = \sum_{t \ge 1} t \cdot (P_{v_1v_1})^{(t-1)} P_{v_1v_2} = \frac{3}{2}$$

(actually, we have the mean of a geometric distribution with parameter $\frac{2}{3}$)

Irreducibility

- Note: A MC can naturally be represented via a <u>directed</u>, weighted graph whose vertices correspond to states and the transition probability P_{ij} is the weight assigned to the edge (i, j). We include only edges (i, j) with $P_{ij} > 0$.
- A state u is <u>reachable</u> from a state v (we write $v \to u$) iff there is a path \mathcal{P} of states from v to u with $\Pr{\mathcal{P}} > 0$.
- A state u communicates with state v iff $u \to v$ and $v \to u$ (we write $u \leftrightarrow v$)
- A MC is called <u>irreducible</u> iff every state can be reached from any other state (equivalently, the directed graph of the MC is strongly connected).

- In our example, v_1 can be reached only from v_2 (and the directed graph is not strongly connected) so the MC is not irreducible.
- Note: In a finite MC, either all states are transient or all states are (non null) persistent.
- Note: In a finite MC which is irreducible, all states are persistent.

- Another type of states: A state *i* is <u>absorbing</u> iff $P_{ii} = 1$ (e.g. in our example, the states v_3 and v_4 are absorbing)
- Another example:



The states v_0, v_n are absorbing

State probability vector

- Definition. Let q^(t) = (q₁^(t), q₂^(t), ..., q_n^(t)) be the row vector whose *i*-th component q_i^(t) is the probability that the MC is in state *i* at time *t*. We call this vector the <u>state</u> probability vector (alternatively, we call it the <u>distribution</u> of the MC at time *t*).
- Main property. Clearly

$$q^{(t)} = q^{(t-1)} \cdot P = q^{(0)} \cdot P^t$$

where P is the transition probability matrix

• Importance: rather than focusing on the probabilities of transitions between the states, this vector <u>focuses on the</u> probability of being in a state.

Definition. A state *i* called <u>periodic</u> iff the largest integer *T* satisfying the property

$$q_i^{(t)} > 0 \Rightarrow t \in \{a + kT | k \ge 0\}$$

is largest than 1 (a > 0 a positive integer); otherwise it is called aperiodic. We call T the periodicity of the state.

• In other words, the MC visits a periodic state only at times which are terms of an arithmetic progress of rate T.

Periodicity (II)

- Example: a random walk on a bipartite graph clearly represents a MC with all states having periodicity 2. Actually, a random walk on a graph is aperiodic <u>iff the</u> graph is not bipartite.
- Definition: We call <u>aperiodic</u> a MC whose states are all aperiodic. Equivalently, the chain is aperiodic iff (gcd: greatest common divisor):

$$\forall x, y : \gcd\{t : P_{xy}^{(t)} > 0\} = 1$$

Ergodicity

- Note: the existence of periodic states introduces significant complications since the MC "oscillates" and does not "converge". The state of the chain at any time clearly depends on the initial state; it belongs to the same "part" of the graph at even times and the other part at odd times.
- Similar complications arise from null persistent states.
- Definition. A state which is non null persistent and aperiodic is called ergodic. A MC whose states are all ergodic is called ergodic.
- Note: As we have seen, a finite, irreducible MC has only non-null persistent states.

Stationarity

Definition: A state probability vector (or distribution) π for which

$$\pi^{(t)} = \pi^{(t)} \cdot P$$

is called stationary distribution

■ Clearly, for the stationary distribution we have

$$\pi^{(t)} = \pi^{(t+1)}$$

In other words, when a chain arrives at a stationary distribution it "stays" at that distribution for ever, so this the "final" behaviour of the chain (i.e. the probability of being at any vertex tends to a <u>well-defined limit</u>, independent of the initial vertex). This is why we also call it <u>equilibrium</u> distribution or <u>steady state</u> distribution. We also say that the chain converges to stationarity.

The Fundamental Theorem of Markov Chains

- In general, <u>a stationary distribution may not exist</u> so we focus on Markov Chains with stationarity.
- Theorem. For every <u>irreducible</u>, <u>finite</u>, aperiodic MC it is:
 - **1** The MC is ergodic.
 - 2 There is a unique stationary distribution π , with $\pi_i > 0$ for all states $i \in S$
 - **3** For all states $i \in S$, it is $f_{ii} = 1$ and $h_{ii} = \frac{1}{\pi_i}$
 - 4 Let N(i, t) the number of times the MC visits state i in t steps. Then

$$\lim_{t \leftarrow \infty} \frac{N(i,t)}{t} = \pi_i$$

Namely, independently of the starting distribution, the MC converges to the stationary distribution.

Stationarity in doubly stochastic matrices

• <u>Definition</u>: A $n \ge n$ matrix M is <u>stochastic</u> if all its entries are non-negative and for each row i, it is:

$$\sum_{j} M_{ij} = 1$$

(i.e. the entries of any row add to 1). If in addition the entries of any column add to 1, i.e. for all j it is:

$$\sum_{i} M_{ij} = 1$$

then the matrix is called doubly stochastic.

• Lemma: The stationary distribution of a Markov Chain whose transition probability matrix P is doubly stochastic is the uniform distribution.

<u>Proof:</u> The distribution $\pi_v = \frac{1}{n}$ for all v is stationary, since it satisfies:

$$[\pi \cdot P]_v = \sum_u \pi_u P_{uv} = \sum_u \frac{1}{n} P_{uv} = \frac{1}{n} \sum_u P_{uv} = \frac{1}{n} 1 = \pi_v \quad \Box$$

Sotiris Nikoletseas, Professor

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Stationarity in symmetric chains

• <u>Definition</u>: A chain is called symmetric iff:

$$\forall u, v : P_{uv} = P_{vu}$$

- <u>Lemma:</u> If a chain is symmetric its stationary distribution is <u>uniform</u>.
- <u>Proof:</u> Let N be the number of states. From Fundamental Theorem, it suffices to check that $\pi_u = \frac{1}{N}$, $\forall u$, satisfies $\pi \cdot P = \pi$. Indeed:

$$(\pi P)_u = \sum_v \pi_v \cdot P_{vu} = \frac{1}{N} \sum_v P_{uv} = \frac{1}{N} \cdot 1 = \pi_u$$

Examples - Card shuffling

Given a set of n cards, let a Markov Chain whose states are all possible permutations of the cards (n!) and one step transition between states defined by some
<u>card shuffling rule</u>. For the shuffling to be effective the stationarity distribution <u>must be the uniform one</u>. We provide two such effective shufflings:

(1) <u>Random transpositions</u>: "choose" any two cards at random and swap them e.g.

 $\cdots \ a \cdots \ b \cdots \Rightarrow \cdots \ b \cdots \ a \cdots$

<u>Note</u>: Indeed the transition probabilities in both directions are the same $\left(\text{each one is } \frac{1}{\binom{n}{2}} \right)$ so the chain is symmetric and its stationary distribution uniform.

(2) <u>Top-in-at-Random</u>: "place the top card to a random new position of the n possible ones"

<u>Note</u>: There are *n* potential new states. Also, each state can be reached from *n* other states with probability $\frac{1}{n}$ from each. So the chain is doubly stochastic and its stationary distribution uniform.

- Although the Fundamental Theorem guarantees that an aperiodic, irreducible finite chain converges to a stationary distribution, it does not tell us <u>how fast convergence</u> happens.
- The convergence rate appropriately close to stationarity is captured by an important measure (the "mixing time").

On the mixing time (II)

- As an example, the number of shufflings needed by "Top-in-at-Random" to produce an almost uniform permutation of cards is O(n log n). Other methods are faster e.g. their mixing time is O(log n), such as in Riffle-Shuffle where the deck of cards is randomly split into two sets (left, right) which are then "interleaved".
- This convergence rate is very important in algorithmic applications, where we want to ensure that a proper sample can be obtained in fairly small time, even when the state space is very large!

Random walks on graphs

• Let G = (V, E) a connected, non-bipartite, undirected graph with *n* vertices. We define a Markov Chain MC_G corresponding to <u>a random walk</u> on the vertices of *G*, with transition probability:

$$P_{uv} = \begin{cases} \frac{1}{d(u)}, & \text{if } uv \in E(G) \\ 0, & \text{otherwise} \end{cases}$$

where d(u) is the degree of vertex u.

• Since the graph is connected and undirected, MC_G is clearly <u>irreducible</u>. Also, since the graph is non-bipartite, MC_G is aperiodic.

The stationary distribution

• So (from fundamental theorem of Markov Chains) M_G has a unique stationary distribution π .

<u>Lemma 1:</u> For all vertices $v \in V$ it is $\pi_v = \frac{d(v)}{2m}$, where *m* is the number of edges of *G*.

<u>Proof:</u> From the definition of stationarity, it must be:

$$\pi_v = [\pi \cdot P]_v = \sum_u \pi_u P_{uv} \quad , \, \forall v \in V$$

Because of uniqueness, it suffices to verify the claimed solution. Indeed, for all $v \in V$ we have (for the claimed solution value):

$$\sum_{u} \pi_{u} P_{uv} = \sum_{u: uv \in E} \frac{d(u)}{2m} \frac{1}{d(u)} = \frac{1}{2m} \sum_{u: uv \in E} 1 = \frac{1}{2m} d(v) = \pi_{v}$$