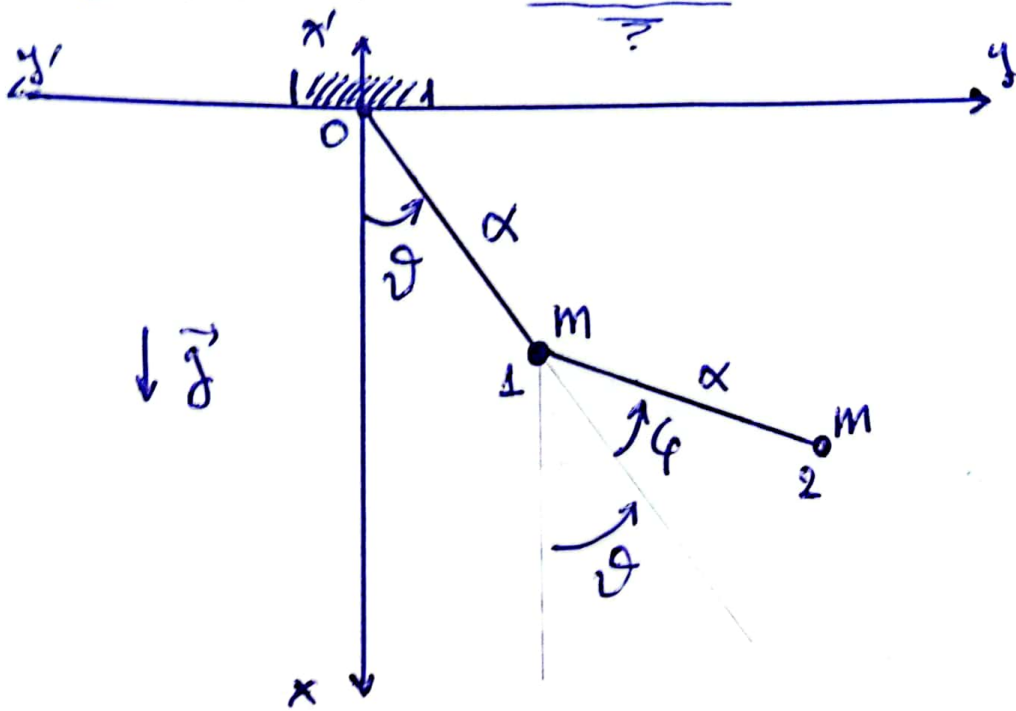


Διπλό εκκρεμές (ειδική περίπτωση)



► Έστω μονάδες $\alpha = m = g = 1$ (1)

► $x_1 = \cos\theta \longrightarrow \dot{x}_1 = -\eta\mu\theta \dot{\theta}$ (2α) (2β)

$x_2 = \cos\theta + \cos(\theta + \phi) \longrightarrow \dot{x}_2 = -\eta\mu\theta \dot{\theta} - \eta\mu(\theta + \phi) \cdot (\dot{\theta} + \dot{\phi})$

$y_1 = \eta\mu\theta \longrightarrow \dot{y}_1 = \cos\theta \dot{\theta}$ (2γ)

$y_2 = \eta\mu\theta + \eta\mu(\theta + \phi) \longrightarrow \dot{y}_2 = \cos\theta \dot{\theta} + \cos(\theta + \phi) \cdot (\dot{\theta} + \dot{\phi})$ (2δ)

► $2K = v_1^2 + v_2^2 = \dot{x}_1^2 + \dot{y}_1^2 + \dot{x}_2^2 + \dot{y}_2^2 =$

$= \dot{\theta}^2 + \dot{\theta}^2 + (\dot{\theta} + \dot{\phi})^2 + 2\dot{\theta}(\dot{\theta} + \dot{\phi}) \cdot \underbrace{[\eta\mu\theta \cdot \eta\mu(\theta + \phi) + \cos\theta \cdot \cos(\theta + \phi)]}_{\cos\theta\cos\phi}$

$= \dot{\phi}^2 + 2\dot{\theta}\dot{\phi} + 3\dot{\theta}^2 + 2\dot{\theta}^2 \cos\theta +$

$+ 2\dot{\theta}\dot{\phi} \cos\theta$ (3)

► $U = -x_1 - x_2 = -2\cos\theta - \cos(\theta + \phi)$ (4)

► $L \equiv K - U \stackrel{(3)}{=} \frac{1}{2} \dot{\phi}^2 + \underline{\dot{\theta}\dot{\phi}} + \frac{3}{2} \dot{\theta}^2 + \dot{\theta} \cos\theta + \underline{\dot{\theta}\dot{\phi} \cos\theta}$
 $- 2\cos\theta - \cos(\theta + \phi)$ (5)

► Λεχόν Χαμιλτων: $0 = \delta I \stackrel{*1}{=} \delta \int L = \int \delta L \stackrel{*2}{=}$

(5) $\int \dot{\varphi} \delta \dot{\varphi} + \dot{\vartheta} \delta \dot{\varphi} + \dot{\varphi} \delta \dot{\vartheta} + 3 \dot{\vartheta} \delta \dot{\vartheta} + \omega \varphi \delta \dot{\vartheta} - \dot{\vartheta} \eta \mu \varphi \delta \varphi$
 $+ \dot{\varphi} \omega \varphi \delta \dot{\vartheta} + \dot{\vartheta} \omega \varphi \delta \dot{\varphi} - \dot{\vartheta} \eta \mu \varphi \delta \varphi + 2 \eta \mu \vartheta \cdot \delta \vartheta$
 $+ \eta \mu (\vartheta + \varphi) (\delta \vartheta + \delta \varphi) =$

$\stackrel{*3}{=} \stackrel{*4}{=} [(\dots) \delta \vartheta + (-||-) \delta \varphi]_{t_A}^{t_B} +$

$+ \int \delta \varphi \cdot (-\ddot{\varphi} - \ddot{\vartheta} - \dot{\vartheta} \eta \mu \varphi - \dot{\vartheta} \omega \varphi + \eta \mu \varphi \dot{\vartheta} \dot{\varphi} - \dot{\vartheta} \eta \mu \varphi) +$
 $+ \delta \vartheta \cdot (-\ddot{\varphi} - 3 \ddot{\vartheta} + \eta \mu \varphi \cdot \dot{\varphi} - \dot{\varphi} \omega \varphi + (\dot{\varphi})^2 \eta \mu \varphi + 2 \eta \mu \vartheta) \Rightarrow$

$\stackrel{*5}{\Rightarrow} \begin{cases} \ddot{\varphi} + \dot{\vartheta} (1 + \omega \varphi) + \eta \mu \varphi \dot{\vartheta} (\dot{\varphi} - 2) = 0 & (6a) \\ \ddot{\varphi} (1 + \omega \varphi) + 3 \ddot{\vartheta} + \eta \mu \varphi \cdot \dot{\varphi} \cdot (\dot{\varphi} + 1) + 2 \eta \mu \vartheta = 0 & (6b) \end{cases}$

► Δοκιμάστε να επαληθεύσετε τις εξισώσεις (6a) & (6b).

► Υποσυνθήκες

- *1 $\int_{t_A}^{t_B} \dots \equiv \int_{t_A}^{t_B} dt \{ \dots \}$ όπου $t_A, t_B > t_A$ τυχαίες στιγμές.
- *2 $\delta L(\varphi, \vartheta, \dot{\varphi}, \dot{\vartheta}) = \frac{\partial L}{\partial \vartheta} \delta \vartheta + \frac{\partial L}{\partial \varphi} \delta \varphi + \frac{\partial L}{\partial \dot{\vartheta}} \delta \dot{\vartheta} + \frac{\partial L}{\partial \dot{\varphi}} \delta \dot{\varphi}$
- *3 $\delta \varphi = \delta \vartheta = 0$ για $t = t_A$ & $t = t_B$.
- *4 $\omega \varphi \delta \dot{\vartheta} = \omega \varphi (\delta \vartheta)' = (\omega \varphi \delta \vartheta)' - (\omega \varphi)' \delta \vartheta$, κ.ο.κ.
- *5 Εφόσον $\delta I = 0$ για τυχαία $\delta \varphi$ & $\delta \vartheta$.