

Subject

ΔΙΦΑΣΙΚΗ ΡΟΗ

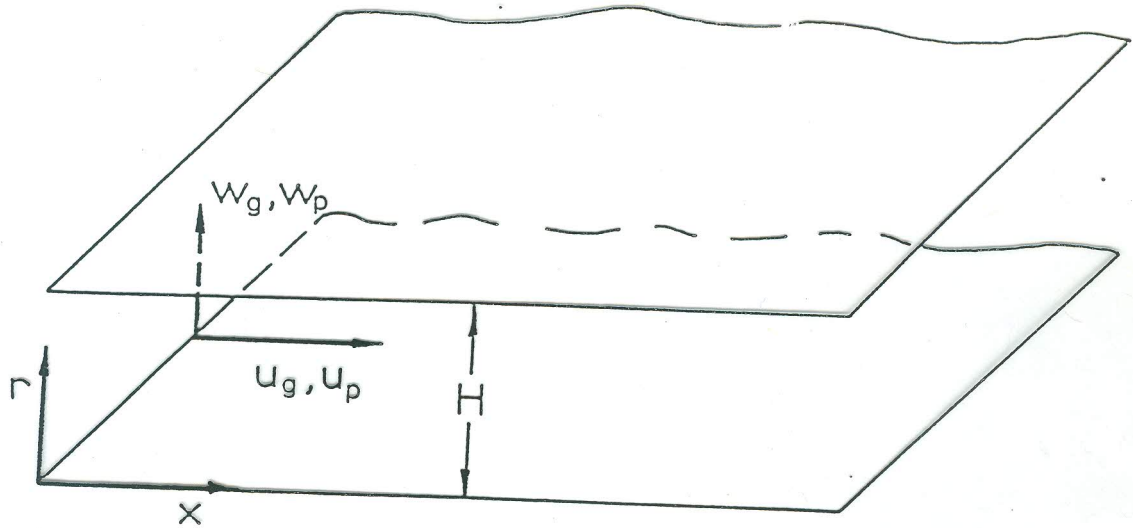
Date

Project

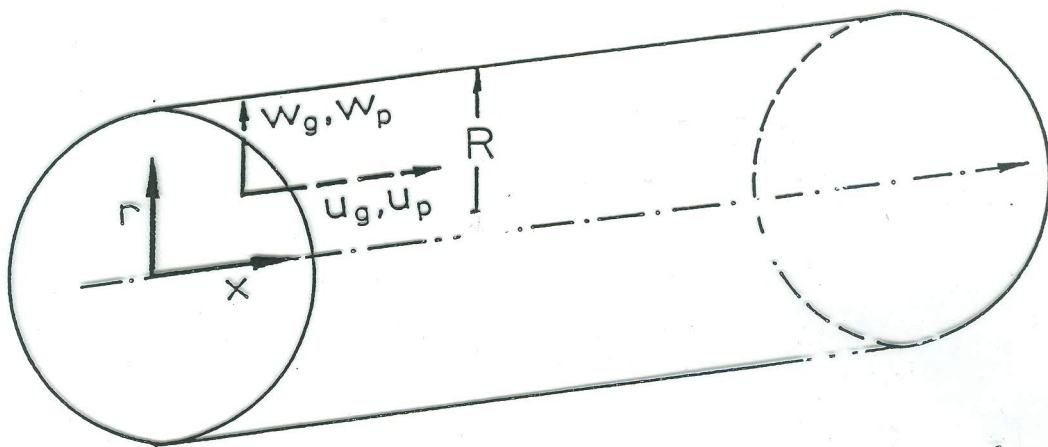
Author

Report

• Ορθογώνιο σύστημα



• Κυλινδρικό σύστημα



Subject ΔΙΦΑΣΙΚΗ ΡΟΗ	Date	Project
	Author	Report

● Εξίσωση συνέχειας

$$\frac{\partial}{\partial x} (\bar{\rho}_r u_r) + \frac{1}{r^k} \frac{\partial}{\partial r} (\bar{\rho}_r w_r r^k) = 0$$

● Εξίσωση ορμής x -διεύθυνση

$$\begin{aligned} \bar{\rho}_r u_r \frac{\partial u_r}{\partial x} + \bar{\rho}_r w_r \frac{\partial u_r}{\partial r} = & - \frac{\partial p_r}{\partial x} + \frac{\partial}{\partial x} \left[2\mu_r \frac{\partial u_r}{\partial x} - \right. \\ & \left. - \frac{2}{3} \mu_r \left(\frac{1}{r^k} \frac{\partial}{\partial r} (r^k w_r) + \frac{\partial u_r}{\partial x} \right) \right] + \frac{1}{r^k} \frac{\partial}{\partial r} \left[r^k \mu_r \left(\frac{\partial u_r}{\partial r} + \right. \right. \\ & \left. \left. + \frac{\partial w_r}{\partial x} \right) \right] + D_{x_r} + L_{x_r} \end{aligned}$$

● Εξίσωση ορμής r -διεύθυνση

$$\begin{aligned} \bar{\rho}_r u_r \frac{\partial w_r}{\partial x} + \bar{\rho}_r w_r \frac{\partial w_r}{\partial r} = & - \frac{\partial p_r}{\partial r} + \frac{1}{r^k} \frac{\partial}{\partial r} \left[2\mu_r r^k \frac{\partial w_r}{\partial r} - \right. \\ & \left. - \frac{2}{3} \mu_r r^k \left(\frac{1}{r^k} \frac{\partial}{\partial r} (r^k w_r) + \frac{\partial u_r}{\partial x} \right) \right] + \frac{\partial}{\partial x} \left[\mu_r \left(\frac{\partial u_r}{\partial r} + \right. \right. \\ & \left. \left. + \frac{\partial w_r}{\partial x} \right) \right] + D_{r_r} + L_{r_r} + G_{r_r} \end{aligned}$$

Subject

ΔΙΦΑΣΙΚΗ ΡΟΗ

Date

Project

Author

Report

• Αδιάστατα μεγέθη

$$\bar{u}_g = \frac{u_g}{u_{gR}}$$

$$\bar{w}_g = \frac{w_g}{u_{gR}}$$

$$\bar{u}_p = \frac{u_p}{u_{gR}}$$

$$\bar{w}_p = \frac{w_p}{u_{gR}}$$

$$\bar{\rho}_g = \frac{\bar{\rho}_g}{\rho_{gR}}$$

$$\bar{\rho}_p = \frac{\bar{\rho}_p}{\rho_{gR}}$$

$$\bar{\mu}_g = \frac{\mu_g}{\mu_{gR}}$$

$$\bar{\mu}_p = \frac{\mu_p}{\mu_{gR}}$$

$$\bar{x} = \frac{x}{L_R}$$

$$\bar{r} = \frac{r}{L_R}$$

$$\bar{r}_p = \frac{r_p}{L_R}$$

$$\bar{p} = \frac{p}{\rho_{gR} u_{gR}^2}$$

• Ταξη μεγέθους των όρων

$$\delta \ll L$$

• χαρακτηριστική ιδιότητα

$$O(1) : \bar{u}_r, \frac{\partial \bar{u}_r}{\partial \bar{x}}, \frac{\partial \bar{w}_r}{\partial \bar{r}}, \frac{\partial^2 \bar{u}_r}{\partial \bar{x}^2}$$

$$O\left(\frac{1}{\delta}\right) : \frac{\partial \bar{u}_r}{\partial \bar{r}}, \frac{\partial^2 \bar{w}_r}{\partial \bar{r}^2}$$

$$O\left(\frac{1}{\delta^2}\right) : \frac{\partial^2 \bar{u}_r}{\partial \bar{r}^2}, Re$$

$$O(\delta) : \bar{w}_r, \frac{\partial \bar{w}_r}{\partial \bar{x}}, \frac{\partial^2 \bar{w}_r}{\partial \bar{x}^2}$$

Subject ΔΙΦΑΣΙΚΗ ΡΟΗ	Date	Project
	Author	Report

● ΕΞΙΣΩΣΗ ΣΥΝΕΧΕΙΑΣ

$$\frac{\partial}{\partial \bar{x}} (\bar{\rho}_r \bar{u}_r) + \frac{1}{\bar{r}^k} \frac{\partial}{\partial \bar{r}} (\bar{\rho}_r \bar{w}_r \bar{r}^k) = 0$$

● ΕΞΙΣΩΣΗ ΟΡΜΗΣ x -ΔΙΕΥΘΥΝΣΗ

$$\bar{\rho}_r \bar{u}_r \frac{\partial \bar{u}_r}{\partial \bar{x}} + \bar{\rho}_r \bar{w}_r \frac{\partial \bar{u}_r}{\partial \bar{r}} = - \frac{\partial \bar{p}_r}{\partial \bar{x}} + \frac{1}{Re_R} \bar{\mu}_r \frac{\partial^2 \bar{u}_r}{\partial \bar{r}^2} +$$

$$+ \frac{1}{Re_R} \frac{\partial \bar{\mu}_r}{\partial \bar{r}} \frac{\partial \bar{u}_r}{\partial \bar{r}} + \frac{1}{Re_R} \frac{k}{\bar{r}} \bar{\mu}_r \frac{\partial \bar{u}_r}{\partial \bar{r}} \pm \frac{3}{8\bar{r}_p} c_{Dx} Z \bar{\rho}_g (\bar{u}_g - \bar{u}_p)^2 \pm$$

$$\pm J_y Z \bar{\rho}_g (\bar{w}_g - \bar{w}_p) \frac{\partial \bar{u}_g}{\partial \bar{r}}$$

● ΕΞΙΣΩΣΗ ΟΡΜΗΣ r -ΔΙΕΥΘΥΝΣΗ

$$0 = - \frac{\partial \bar{p}_r}{\partial \bar{r}} \pm \frac{3}{8\bar{r}_p} c_{Dr} Z \bar{\rho}_g (\bar{w}_g - \bar{w}_p)^2 \pm$$

$$\pm J_y Z \bar{\rho}_g (\bar{u}_g - \bar{u}_p) \frac{\partial \bar{u}_g}{\partial \bar{r}} - G_r$$

$$G_p = \frac{Z}{F_{rR}} (\bar{\rho}_p - \bar{\rho}_g)$$

$$G_g = \frac{Z}{F_{rR}} \bar{\rho}_g$$

$$Re_R = \frac{\rho_{gR} u_{gR} L_R}{\mu_{gR}}$$

$$F_{rR} = \frac{u_{gR}^2}{g L_R}$$

Subject

ΔΙΦΑΣΙΚΗ ΡΟΗ

Date

Project

Author

Report

• Αρχικές και Οριακές Συνθήκες

$$\bar{p} = \bar{p}(\bar{r}, 0) = \bar{p}_{\sigma\tau\alpha\theta}$$

$$\bar{M} = \bar{M}(\bar{r}, 0)$$

$$\frac{\partial \bar{u}_r}{\partial \bar{r}} = 0 \quad \text{και} \quad \bar{w}_r = 0$$

$$\frac{\partial \bar{\rho}_r \bar{u}_r}{\partial \bar{x}} + 2^k \frac{\partial \bar{\rho}_r \bar{w}_r}{\partial \bar{r}} = 0$$

$$\bar{\rho}_r \bar{u}_r \frac{\partial \bar{u}_r}{\partial \bar{x}} = - \frac{\partial \bar{p}_r}{\partial \bar{x}} + \frac{2\bar{\mu}_r}{\text{Re}_R} \frac{\partial^2 \bar{u}_r}{\partial \bar{r}^2} + \frac{3}{8\bar{r}_p} c_{Dx} 2\bar{\rho}_g (\bar{u}_g - \bar{u}_p)^2$$

$$\bar{u}_r(x, R) = 0 \quad \text{και} \quad \bar{w}_r(x, R) = 0$$

Subject	Date	Project
	Author	Report

ΣΥΣΤΗΜΑ ΕΞΙΣΩΣΕΩΝ ΓΙΑ ΤΥΡΒΩΔΗ ΡΟΗ

$$u_r = \bar{u}_r + u'_r \quad w_r = \bar{w}_r + w'_r \quad p = \bar{p} + p'$$

$$\bar{\rho}_r \bar{u}_r \frac{\partial \bar{u}_r}{\partial x} + \bar{\rho}_r \bar{w}_r \frac{\partial \bar{u}_r}{\partial r} = - \frac{\partial \bar{p}_r}{\partial x} + \frac{1}{Re_R} \frac{1}{r^k} \frac{\partial}{\partial r} (\mu_r^k \frac{\partial \bar{u}_r}{\partial r}) \pm$$

$$\pm \frac{3}{8r_p} c_{Dx} Z \rho_g [(\bar{u}_g - \bar{u}_p)^2 + (\bar{u}'_g - \bar{u}'_p)^2] \pm$$

$$\pm J_y Z \rho_g [(\bar{w}_g - \bar{w}_p) \frac{\partial \bar{u}_g}{\partial r} + (\bar{w}'_g - \bar{w}'_p) \frac{\partial \bar{u}'_g}{\partial r}] - \rho_r \frac{\partial u'_r}{\partial x} - \rho_r \frac{\partial u'_r w'_r}{\partial r}$$

$$\bar{\rho}_r \bar{u}_r \frac{\partial \bar{u}_r}{\partial x} + \bar{\rho}_r \bar{w}_r \frac{\partial \bar{u}_r}{\partial r} = - \frac{\partial \bar{p}_r}{\partial x} + \frac{1}{Re_R} \frac{1}{r^k} \frac{\partial}{\partial r} (\mu_r^k \frac{\partial \bar{u}_r}{\partial r}) \pm$$

$$\pm \frac{3}{8r_p} c_{Dx} Z \rho_g (\bar{u}_g - \bar{u}_p)^2 \pm J_y Z \rho_g (\bar{w}_g - \bar{w}_p) \frac{\partial \bar{u}_g}{\partial r} - \frac{\partial}{\partial r} (\rho_r \bar{u}'_r w'_r)$$

$$\tau_t = - \overline{\rho_r u'_r w'_r} = \mu_t \frac{\partial \bar{u}_r}{\partial r}$$

$$\tau_{o\lambda} = \tau_l + \tau_t = \mu_l \frac{\partial \bar{u}_r}{\partial r} + \mu_t \frac{\partial \bar{u}_r}{\partial r} = (\mu_l + \mu_t) \frac{\partial \bar{u}_r}{\partial r}$$

Subject	Date	Project
	Author	Report

ΣΤΡΩΤΗ ΡΟΗ

● Αέρας

$$\frac{\mu_g}{\mu_{g0}} = \frac{S+T_o}{S+T} \left(\frac{T}{T_o}\right)^{1.5}$$

σχέση Sutherland

$$S = 123.6 \text{ K}$$

$$\mu_g = \frac{\beta T^{1.5}}{S+T}$$

$$\beta = 1.458 \times 10^{-6}$$

$$S = 110.4 \text{ K}$$

● Σωματίδια

$$v_m = \frac{v_g}{1+n}$$

σχέση Pai

$$n = \frac{k_p}{1-k_p}$$

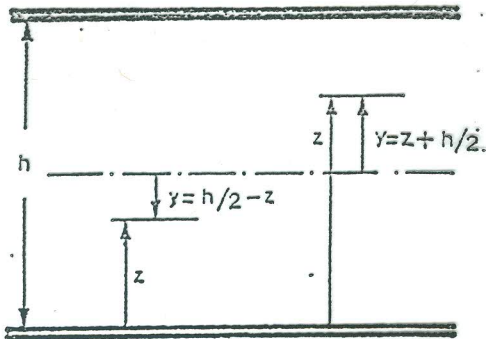
και

$$k_p = \frac{Z\rho_{sp}}{Z\rho_{sp} + (1-Z)\rho_g} = \frac{\bar{\rho}_p}{\rho_m}$$

$$\mu_m = \mu_g - Z\mu_g$$

$$\mu_p = Z\mu_g$$

Subject	Date	Project
	Author	Report



Σχ. 1. Επεξήγηση των διαφόρων συντεταγμένων.

$$\tau_t = \tau_0 \frac{y}{h/2}$$

όπου $y = |z - h/2|$ με $y = 0$ για $z = h/2$.

$$\tau_t = 2 \tau_0 \bar{y}$$

όπου $\bar{y} = |\bar{z} - 1/2|$ με $\bar{y} = y/h$ και $\bar{z} = z/h$.

σχέση του Boussinesq

$$\tau_{tg} = \mu_{tg} \frac{d\bar{u}_g}{dz}$$

$$\mu_{tg} = \frac{\tau_{tg}}{d\bar{u}_g/dz} = \frac{2\tau_{og}\bar{y}}{d\bar{u}_g/dz}$$

$$\tau_{og} = 0,332 \rho_{gR} u_{gR}^2 Re_x^{-1/2}$$

$$Re_x = \frac{\rho_{gR} u_{gR} x}{\mu_{gR}}$$

$$\tau_{tp} = \mu_{tp} \frac{d\bar{u}_p}{dz}$$

$$\mu_{tp} = \frac{\tau_{tp}}{d\bar{u}_p/dz} = \frac{2\tau_{op}\bar{y}}{d\bar{u}_p/dz}$$

$$\tau_{ogp} = \frac{0,332 \rho_{gR} u_{gR}^2}{Re_x^{1/2}} [1+n]^{1/2} \left[1 + 0,49 \frac{Lv}{x} \frac{n}{1+n} \right]$$

$$n = \frac{Z\rho_p}{(1-Z)\rho_g}$$

Subject	Date	Project
	Author	Report

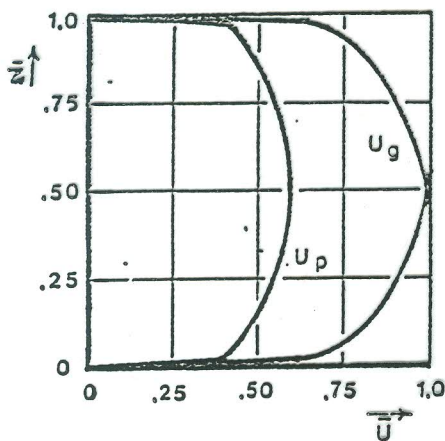
$$Lv = \frac{4\rho_p d_p^2 u_{gR}}{18\mu_{gR}}$$

$$\tau_{ogp} = \tau_{og} + \tau_{op}$$

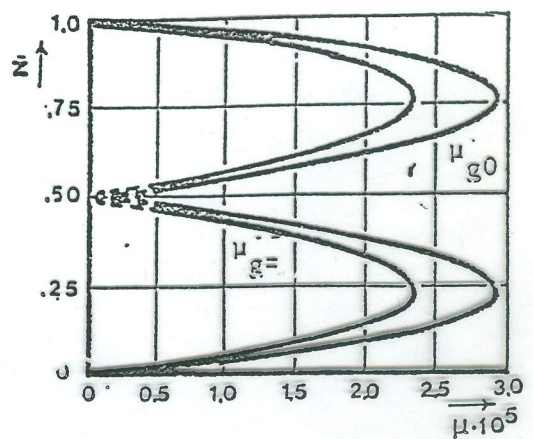
$$\tau_{op} = \tau_{ogp} - \tau_{og}$$

$$\tau_{op} = \frac{0.332\rho_{gR}u_{gR}^2}{Re_x^{1/2}} \left[(1+n)^{1/2} \left(1 + 0.49 \frac{Lv}{x} \frac{n}{1+n} \right) - 1 \right]$$

$$\left(\frac{du}{dz} \right)_i = \frac{u_{i+1} - u_{i-1}}{2\Delta z}$$

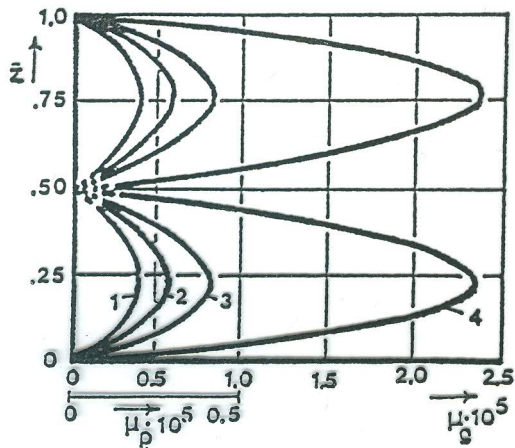


Σχ. 8. Κατανομές ταχύτητας αέρα και σωματιδίων για τον υπολογισμό του λεώδους.

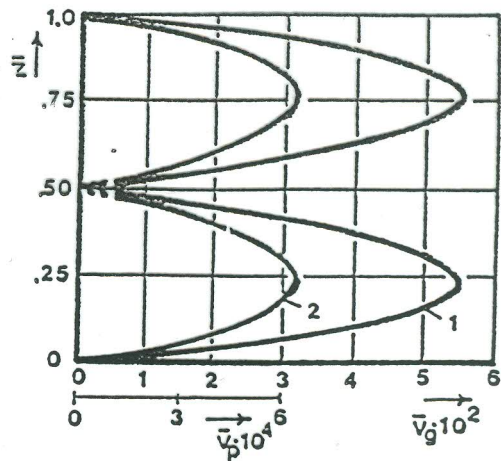


Σχ. 9. Κατανομή λεώδους αέρα για ροή σε κυκλικό αγωγό μ_{g0} , και για ροή σε παράλληλες πλάκες $\mu_{g=}$.

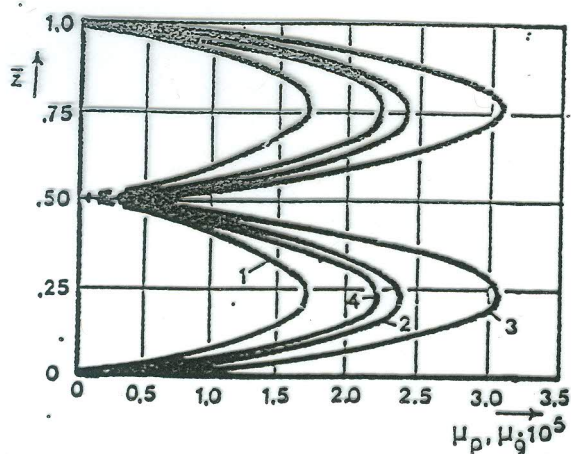
Subject	Date	Project
	Author	Report



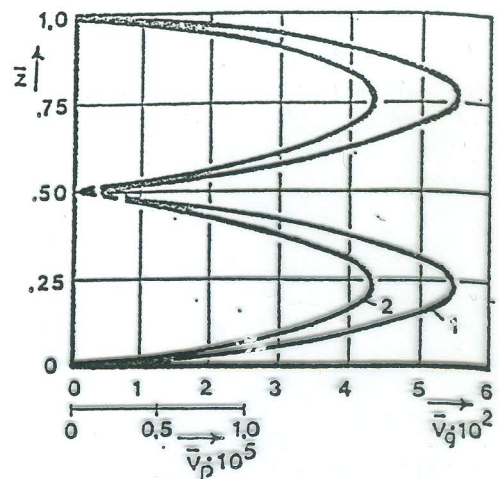
Σχ.10. Κατανομές λεώδους αέρα και σωματιδίων για αραιή πνευματική μεταφορά
(1: $\rho_p = 1250$, 2: $\rho_p = 1800$
3: $\rho_p = 2600$, 4: $\rho_g = 1,2 \text{ kg/m}^3$)



Σχ.11. Κατανομή κινηματικού λεώδους αέρα σωματιδίων σε αδιάστατη μορφή.
(Στή καμπύλη 2 συμπίπτουν οι κατανομές και των τριών σωματιδίων του σχ.10)



Σχ.12. Κατανομές λεώδους αέρα και σωματιδίων για πυκνή πνευματική μεταφορά
(1: $\rho_p = 1250$, 2: $\rho_p = 1800$, 3: $\rho_p = 2600$, 4: $\rho_g = 1,2 \text{ kg/m}^3$)



Σχ.13. Κατανομή κινηματικού λεώδους αέρα σωματιδίων σε αδιάστατη μορφή.
(Στή καμπύλη 2 συμπίπτουν οι κατανομές και των τριών σωματιδίων του σχ.12).