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• Θεωρία Συνεχούς Μάζου

ρευστό - ψευδορευστό  
g ρ

φάση r : q r , T r , ρ r , ρ r

• Μαζα μίγματος

$$M = M_p + M_g$$

• Όγκος μίγματος

$$V = V_p + V_g$$

• Όγκος σωματιδίων

$$V_p = n_p V_s$$

• Μαζα σωματιδίων

$$M_p = m_p n_p V$$

• Πυκνότητα σωματιδίων

φασική  
μερική

$$\rho_{sp} = \frac{M_p}{V_p} = \frac{m_p}{V_s}$$

$$\bar{\rho}_p = \frac{M_p}{V} = m_p n_p = \rho_{sp} V_s n_p = \rho_{sp} Z$$

• Πυκνότητα αέρα

φασική  
μερική

$$\rho_g = \frac{M_g}{V_g}$$

$$\bar{\rho}_g = \frac{M_g}{V} = \frac{M_g}{V_g} \frac{V_g}{V} = (1-Z)\rho_g$$

• Ογκομετρική συγκεντρωση

$$Z = \frac{V_p}{V}$$

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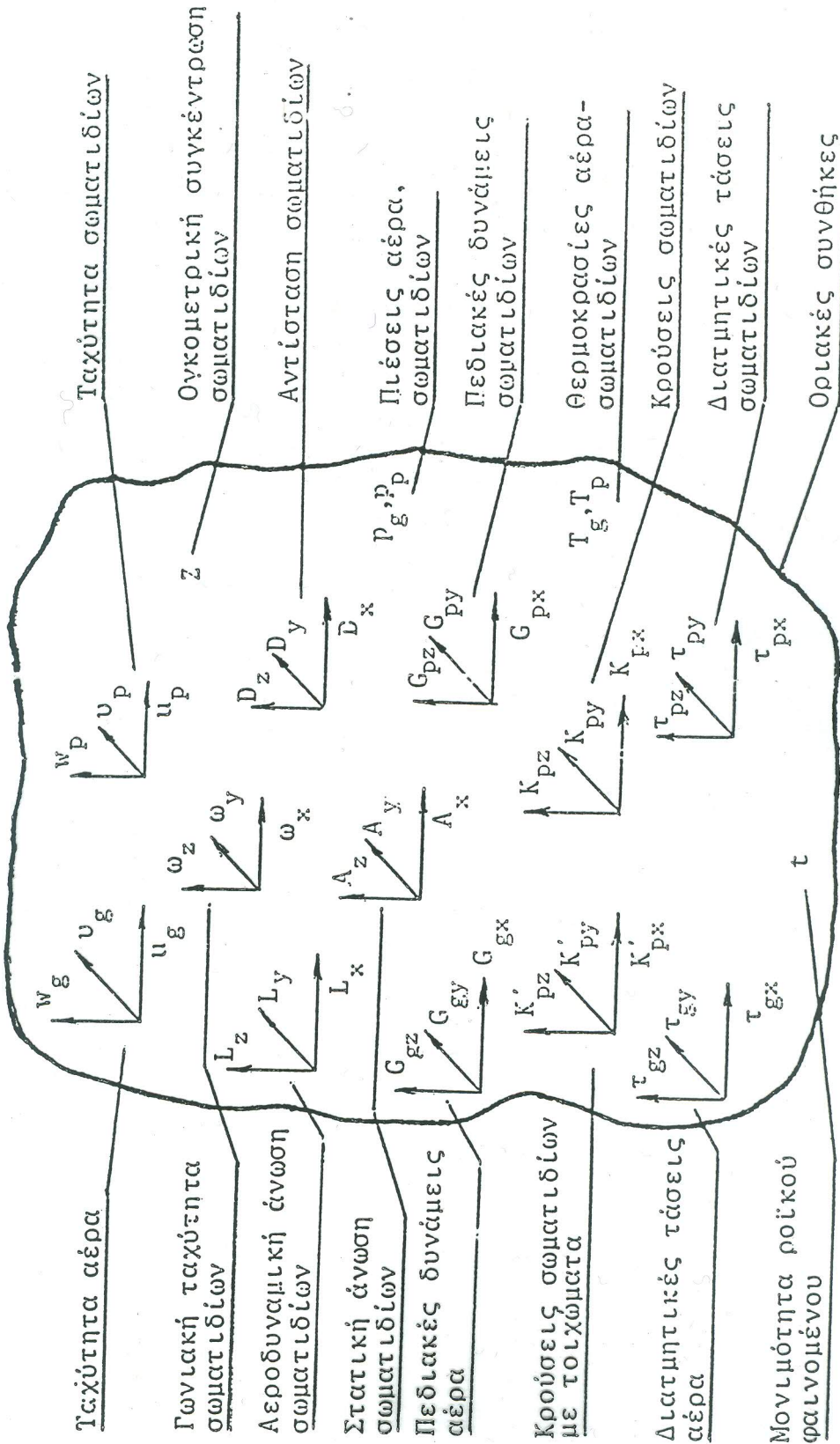
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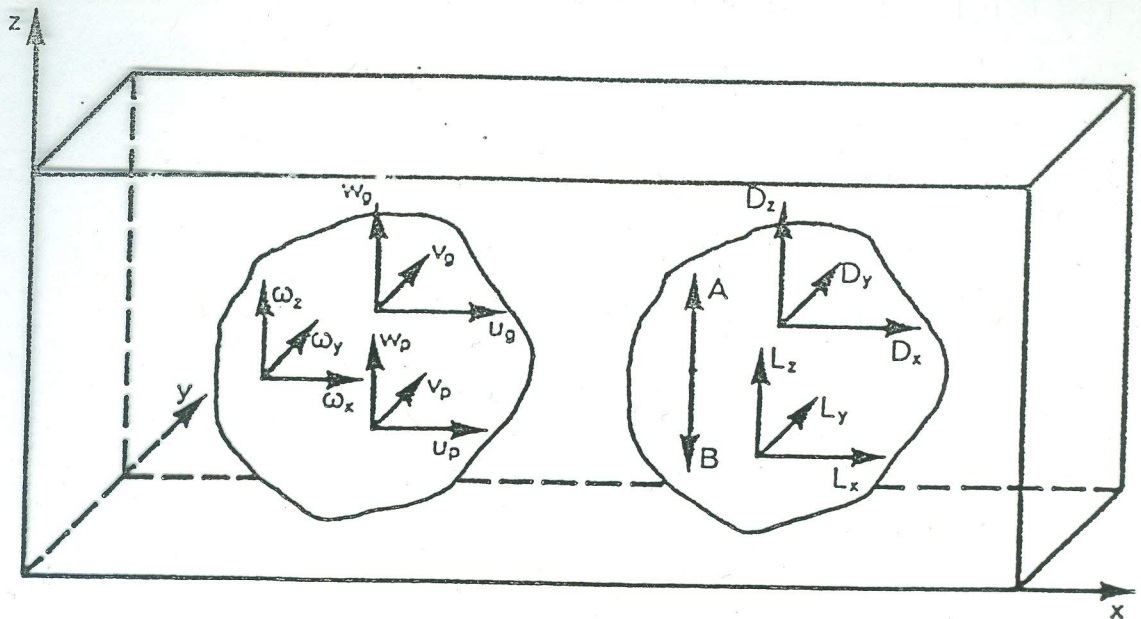
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● Καταστατική εξίσωση

$$p_g = \bar{\rho}_g RT_g = (1-Z)p$$

$$p_p = Zp$$

$$p = p_g + p_p$$

$$\rho_{sp} = \text{σταθ.}$$

● Εξίσωση συνέχειας

$$\frac{\partial \bar{\rho}_r}{\partial t} + \frac{\partial (\bar{\rho}_r u_r^i)}{\partial x^i} = 0$$

$$\vec{q}_r = \bar{i}u_r + \bar{j}v_r + \bar{k}w_r$$

● Εξίσωση ορμης

$$\bar{\rho}_r \left( \frac{\partial}{\partial t} + u_r^i \frac{\partial}{\partial x^i} \right) \vec{q}_r = \bar{\rho}_r \frac{D_r \vec{q}_r}{Dt} = -\nabla p_r + \nabla \cdot \tau_r + \vec{F}_{br} + \vec{F}_r$$

● Εξίσωση ενέργειας

$$\frac{D}{Dt} \left[ \bar{\rho}_r \left( u_{mr} + \frac{1}{2} q_r^2 + \phi_r \right) \right] + \frac{\partial}{\partial x^j} \left[ \delta^{ij} u_r^i p_r - u_r^i \tau_r^{ij} - Q_{cr}^j \right] = k_T \Delta T$$

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● Γενική σχέση αντίστασης

$$\vec{F}_p = \vec{D} = c_{Dn} \frac{1}{2} \rho_g (\vec{q}_g - \vec{q}_p)^2 A_p = c_{Dn} \rho_p d_p A_p$$

● Σχέσεις υπολογισμού  $c_D$

$$c_D = \frac{24}{Re_p} \quad \vec{F}_p = 6\pi r_p \mu_g n_p (\vec{q}_g - \vec{q}_p) = \frac{1}{2} c_{Dn} A_p \rho_g \vec{C}^2$$

$$c_D = \frac{24}{Re_p} \left(1 + \frac{3}{16} Re_p\right)$$

$$c_D = \frac{24}{Re_p} + \frac{4}{\sqrt{Re_p}} + 0.4$$

$$Re_{px} = \frac{(u_g - u_p) \rho_g d_p}{\mu_g}$$

$$D_x = c_{Dxn} \frac{1}{2} (u_g - u_p)^2 A_p = c_{Dxn} \rho_p d_x A_p$$

● Μη σφαιρικά σωματίδια

σφαιρικότητα  $\Phi = \frac{\pi \left(\frac{6\nu^{2/3}}{\pi S}\right)}{S_p} = (6\sqrt{\pi})^{2/3} \cdot \frac{\nu^{2/3}}{S_p} = \frac{\pi D_{1\sigma}^2}{S_p}$

σχέση Muschelknautz

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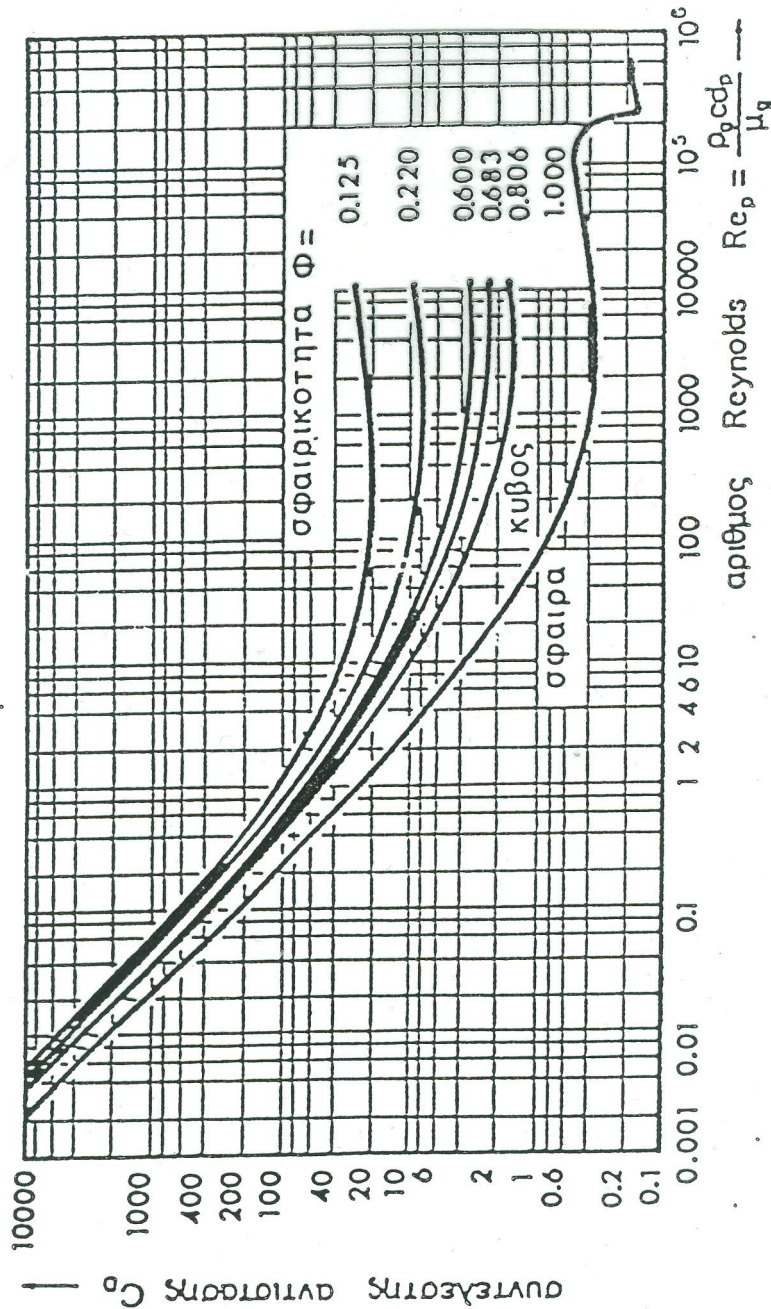
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| σχημα σωματιδίου               | σφαιρικότητα |
|--------------------------------|--------------|
| σφαιρα                         | 1.           |
| οκταεδρο                       | 0.847        |
| κυβος                          | 0.806        |
| πρισματα                       |              |
| α x α x 2α                     | 0.767        |
| α x 2α x 2α                    | 0.761        |
| α x 2α x 3α                    | 0.725        |
| κυλινδροι                      |              |
| h = 2r                         | 0.874        |
| h = 3r                         | 0.860        |
| h = 10r                        | 0.691        |
| h = 20r                        | 0.580        |
| δισκοι                         |              |
| h = 1.33 r                     | 0.858        |
| h = r                          | 0.827        |
| h = r/3                        | 0.594        |
| h = r/10                       | 0.323        |
| h = r/15                       | 0.254        |
| ελλειψοειδες<br>εκ περιστροφης |              |
| λ = 3d                         | 0.683        |

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• σχέση

Muschelknautz

$$c_D = \sum_{j=1}^3 A_j Re_p^{\frac{j-3}{2}}$$

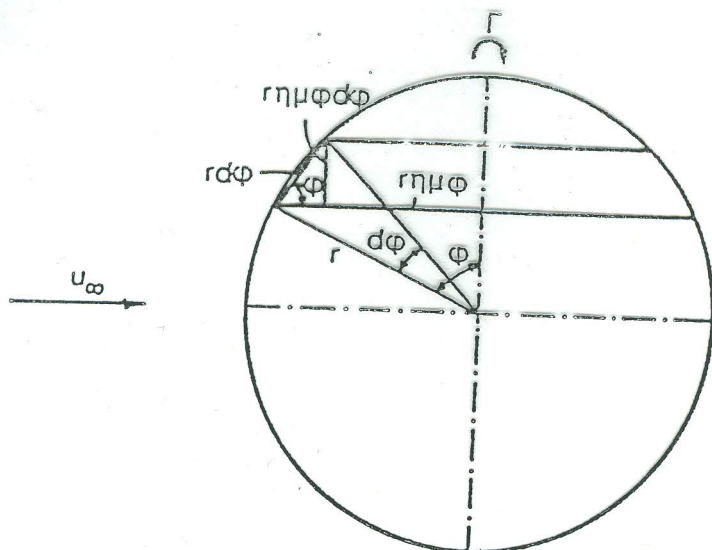
$$A_j \quad | \quad j=1, 2, 3$$

$$Re_p = \frac{\rho_g (u_g - u_p) d_p}{\mu_g}$$

ΠΙΝΑΚΑΣ 1. Τιμές των συντελεστών  $A_j$  για τον υπολογισμό του συντελεστή αντίστασης σωματιδίων διαφόρων σχημάτων

| Συντελεστές |       |       | Περιοχή<br>$Re_p$   | Χαρακτηριστικό<br>μεγεθος σωματ. | Σχημα<br>σωματιδ. | Αναφορά  |
|-------------|-------|-------|---------------------|----------------------------------|-------------------|----------|
| $A_1$       | $A_2$ | $A_3$ |                     |                                  |                   |          |
| 24          | 0     | 0     | $Re_p < 1$          | διαμετρος, $d_p$                 | σφαιρα            | Stokes   |
| 24          | 4     | 0.4   | $Re_p < 10^4$       | διαμετρος, $d_p$                 | σφαιρα            | Molérus  |
| 21.5        | 6.5   | 0.23  | $0.5 < Re_p < 1000$ | διαμετρος, $d_p$                 | σφαιρα            | Muschel. |
| 24          | 6     | 0.35  | $0.5 < Re_p < 800$  | 1.1*μεγ.διαστ.                   | πολυεδρο          | >>       |
| 23          | 6     | 0.5   | $0.5 < Re_p < 600$  | 1.08*διαμ.βασης                  | κυλινδρος         | >>       |
| 27          | 4.5   | 0.65  | $0.5 < Re_p < 400$  | 1.24*ακμη                        | κυβος             | >>       |

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● Γενική σχέση ανώσης

$$L = c_{Lid} \frac{1}{2} \rho u^2 A_p$$

● Συντελεστής ανώσης

$$c_{Lid} = \frac{16}{3} \frac{\omega r_D}{u_\infty} = \frac{16}{3} M_{Re}$$

$$M_{Re} = \frac{Re_{Rot}}{Re_{Tran}} = \frac{\frac{\rho_g d \omega r_D}{\mu_g}}{\frac{\rho_g d u_\infty}{\mu_g}} = \frac{\omega r_D}{u_\infty}$$

$$L_x = \frac{16}{3} n_p A_p \left[ \frac{J_z r_D^3 dy}{u_g - u_p} \frac{1}{2} \left( \frac{\partial u_g}{\partial x} - \frac{\partial u_p}{\partial y} \right) + \frac{J_y r_D^3 dz}{w_g - w_p} \frac{1}{2} \left( \frac{\partial u_g}{\partial z} - \frac{\partial w_p}{\partial x} \right) \right]$$



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$$\vec{\omega} = \omega_x \vec{i} + \omega_y \vec{j} + \omega_z \vec{k}$$

γωνιακή ταχύτητα αερα

$$\omega_x = \frac{1}{2} \left( \frac{\partial w}{\partial y} - \frac{\partial u}{\partial z} \right)$$

$$\omega_y = \frac{1}{2} \left( \frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right)$$

$$\omega_z = \frac{1}{2} \left( \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \right)$$

$$\vec{\omega}' = \omega'_x \vec{i} + \omega'_y \vec{j} + \omega'_z \vec{k}$$

γωνιακή ταχύτητα σωματιδίων

$$\omega'_x = J_x \omega_x$$

$$\omega'_y = J_y \omega_y$$

$$\omega'_z = J_z \omega_z$$

κυκλοφορία

$$dL = \rho_g u_\infty \Gamma r_p \eta \mu \phi d\phi$$

$$\Gamma = 2\pi \omega r_p^2 \eta \mu^2 \phi$$

$$L = \int_0^\pi 2\pi \omega \rho_g u_\infty r_p^3 \eta \mu^3 \phi d\phi$$

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• ΣΥΝΤΕΛΕΣΤΗΣ ΑΔΡΑΝΕΙΑΣ ΣΩΜΑΤΙΔΙΩΝ

$$\vec{T} = -8 \mu \pi \omega_0 r_p^3$$

$$\vec{T}_p = \vec{T}_g$$

$$\vec{T}_p = I_p \vec{\alpha}_p$$

$$\vec{T}_g = I_g \vec{\alpha}_g$$

$$I_p \vec{\alpha}_p = I_g \vec{\alpha}_g \quad \eta \quad \frac{I_g}{I_p} = \frac{\vec{\alpha}_p}{\vec{\alpha}_g}$$

$$I_g = \frac{2}{5} m_g r_g^2$$

$$\mu \epsilon \quad m_g = \rho_g V_g$$

$$I_p = \frac{2}{5} m_p r_p^2$$

$$\mu \epsilon \quad m_p = \rho_p V_p$$

$$\frac{I_g}{I_p} = \frac{\rho_g}{\rho_p} = \frac{\vec{\alpha}_p}{\vec{\alpha}_g}$$

$$\vec{\alpha}_p = \frac{\rho_g}{\rho_p} \vec{\alpha}_g$$

$$\frac{d\vec{\omega}_p}{dt} = \frac{\rho_g}{\rho_p} \frac{d\vec{\omega}_g}{dt}$$

$$\vec{\omega}_p = \frac{\rho_g}{\rho_p} \vec{\omega}_g$$

$$\vec{\omega}_p = J \vec{\omega}_g$$

$$J = \rho_g / \rho_p$$

$$J_x = J_y = J_z = J$$

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● Στατική ανώση

$$\vec{F}_{p(b)} = -z\rho_g \vec{g}$$

● Πεδιακές δυνάμεις

$$\vec{F}_{bp(grav)} = \bar{\rho}_p \vec{g} = z\rho_{sp} \vec{g}$$

$$\vec{F}_{bg(grav)} = \bar{\rho}_g \vec{g} = (1-z)\rho_g \vec{g}$$

● Συνδυασμός

$$\vec{F}_{bp(grav)} + \vec{F}_{p(b)} = z\rho_{sp} \vec{g} - z\rho_g \vec{g} = z(\rho_{sp} - \rho_g) \vec{g}$$

$$\vec{F}_{bg(grav)} + \vec{F}_{g(b)} = (1-z)\rho_g \vec{g} + z\rho_g \vec{g} = \rho_g \vec{g}$$

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• σωματίδια

$$\begin{aligned}
 z\rho_{sp} \left( \frac{\partial u_p}{\partial t} + u_p \frac{\partial u_p}{\partial x} + v_p \frac{\partial u_p}{\partial y} + w_p \frac{\partial u_p}{\partial z} \right) &= - \frac{\partial p_p}{\partial x} + \\
 + \frac{\partial}{\partial x} \left[ 2\mu_p \frac{\partial u_p}{\partial x} - \frac{2}{3}\mu_p \left( \frac{\partial u_p}{\partial x} + \frac{\partial v_p}{\partial y} + \frac{\partial w_p}{\partial z} \right) \right] &+ \\
 + \frac{\partial}{\partial y} \left[ \mu_p \left( \frac{\partial u_p}{\partial y} + \frac{\partial v_p}{\partial x} \right) \right] + \frac{\partial}{\partial z} \left[ \mu_p \left( \frac{\partial w_p}{\partial x} + \frac{\partial v_p}{\partial z} \right) \right] &+ c_{Dx} n_p A_p P_{dx} \\
 + \left[ \left( \frac{\partial u_g}{\partial x} - \frac{\partial u_g}{\partial y} \right) \frac{J_z P_{dx}}{u_g - u_p} + \left( \frac{\partial u_g}{\partial z} - \frac{\partial w_g}{\partial x} \right) \frac{J_y P_{dz}}{w_g - w_p} \right] \frac{8}{3} n_p r_p A_p &:
 \end{aligned}$$

• αερας

$$\begin{aligned}
 (1-z)\rho_g \left( \frac{\partial u_g}{\partial t} + u_g \frac{\partial u_g}{\partial x} + v_g \frac{\partial u_g}{\partial y} + w_g \frac{\partial u_g}{\partial z} \right) &= - \frac{\partial p_g}{\partial x} + \\
 + \frac{\partial}{\partial x} \left[ 2\mu_g \frac{\partial u_g}{\partial x} - \frac{2}{3}\mu_g \left( \frac{\partial u_g}{\partial x} + \frac{\partial v_g}{\partial y} + \frac{\partial w_g}{\partial z} \right) \right] &+ \\
 + \frac{\partial}{\partial y} \left[ \mu_g \left( \frac{\partial u_g}{\partial y} + \frac{\partial v_g}{\partial x} \right) \right] + \frac{\partial}{\partial z} \left[ \mu_g \left( \frac{\partial w_g}{\partial x} + \frac{\partial v_g}{\partial z} \right) \right] &- c_{Dx} n_p A_p P_{dx} \\
 - \left[ \left( \frac{\partial u_g}{\partial x} - \frac{\partial u_g}{\partial y} \right) \frac{J_z P_{dy}}{u_g - u_p} + \left( \frac{\partial u_g}{\partial z} - \frac{\partial w_g}{\partial x} \right) \frac{J_y P_{dz}}{w_g - w_p} \right] \frac{8}{3} \mu_p r_p A_p &
 \end{aligned}$$

$$\tau_r^{ij} = \mu_r \left[ \left( \frac{\partial u_r^i}{\partial x^j} + \frac{\partial u_r^j}{\partial x^i} \right) - \frac{2}{3} \left( \frac{\partial u_r^k}{\partial x^k} \right) \delta^{ij} \right]$$

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$$\begin{aligned}
 & z\rho_{sp}c_{pp}\left(\frac{\partial T_p}{\partial t} + u_p\frac{\partial T_p}{\partial x} + v_p\frac{\partial T_p}{\partial y} + w_p\frac{\partial T_p}{\partial z}\right) - \frac{\partial p_p}{\partial t} - u_p\frac{\partial p_p}{\partial x} - \\
 & - v_p\frac{\partial p_p}{\partial y} - w_p\frac{\partial p_p}{\partial z} - \frac{\partial}{\partial x}\left(k_p\frac{\partial T_p}{\partial x}\right) - \frac{\partial}{\partial y}\left(k_p\frac{\partial T_p}{\partial y}\right) - \frac{\partial}{\partial z}\left(k_p\frac{\partial T_p}{\partial z}\right) - \\
 & - \mu\phi_p + c_{Dx}u_p n_p A_p p_p dx + c_{Dy}v_p n_p A_p p_p dy + c_{Dz}w_p n_p A_p p_p dz + \\
 & + \left[\left(\frac{\partial u_g}{\partial x} - \frac{\partial u_g}{\partial y}\right)\frac{J_z p dy}{u_g - u_p} + \left(\frac{\partial u_g}{\partial z} - \frac{\partial w_g}{\partial x}\right)\frac{J_y p dz}{w_g - w_p}\right] \frac{8}{3} n_p r_p A_p u_p + \\
 & + \left[\left(\frac{\partial u_g}{\partial x} - \frac{\partial u_g}{\partial y}\right)\frac{J_z p dx}{u_g - u_p} + \left(\frac{\partial w_g}{\partial y} - \frac{\partial u_g}{\partial z}\right)\frac{J_x p dz}{w_g - w_p}\right] \frac{8}{3} n_p r_p A_p u_p + \\
 & + \left[\left(\frac{\partial u_g}{\partial z} - \frac{\partial w_g}{\partial x}\right)\frac{J_y p dx}{u_g - u_p} + \left(\frac{\partial w_g}{\partial y} - \frac{\partial u_g}{\partial z}\right)\frac{J_x p dy}{u_g - u_p}\right] \frac{8}{3} n_p r_p A_p w_p + \\
 & + z\rho_g g w_p + z\rho_{sp} g w_p = k_T (T_g - T_p)
 \end{aligned}$$

$$\begin{aligned}
 \phi_p = & 2\left[\left(\frac{\partial u_p}{\partial x}\right)^2 + \left(\frac{\partial u_p}{\partial y}\right)^2 + \left(\frac{\partial w_p}{\partial z}\right)^2\right] + \left[\frac{\partial u_p}{\partial x} + \frac{\partial u_p}{\partial y}\right]^2 + \\
 & + \left[\frac{\partial w_p}{\partial y} + \frac{\partial u_p}{\partial z}\right]^2 + \left[\frac{\partial u_p}{\partial z} + \frac{\partial w_p}{\partial x}\right]^2 - \frac{2}{3}\left[\frac{\partial u_p}{\partial x} + \frac{\partial u_p}{\partial y} + \frac{\partial w_p}{\partial z}\right]^2
 \end{aligned}$$