

## 10 APPENDIX: Technical results

### 10.1 The inverse function theorem

**Lemma 10.1** (*Contraction mapping principle*) *Let  $M$  be a complete metric space and suppose  $T : M \rightarrow M$  is a map such that*

$$d(Tx, Ty) \leq kd(x, y)$$

where  $k < 1$ . Then  $T$  has a unique fixed point.

**Proof:** Choose any point  $x_0$ , then

$$\begin{aligned} d(T^m x_0, T^n x_0) &\leq k^m d(x_0, T^{n-m} x_0) \quad \text{for } n \geq m \\ &\leq k^m (d(x_0, Tx_0) + d(Tx_0, T^2 x_0) + \dots + d(T^{n-m-1} x_0, T^{n-m} x_0)) \\ &\leq k^m (1 + k + \dots + k^{n-m-1}) d(x_0, Tx_0) \\ &\leq \frac{k^m}{1-k} d(x_0, Tx_0) \end{aligned}$$

This is a Cauchy sequence, so completeness of  $M$  implies that it converges to  $x$ . Thus  $x = \lim T^n x_0$  and so by continuity of  $T$ ,

$$Tx = \lim T^{n+1} x_0 = x$$

For uniqueness, if  $Tx = x$  and  $Ty = y$ , then

$$d(x, y) = d(Tx, Ty) \leq kd(x, y)$$

and so  $k < 1$  implies  $d(x, y) = 0$ . □

**Theorem 10.2** (*Inverse function theorem*) *Let  $U \subseteq \mathbf{R}^n$  be an open set and  $f : U \rightarrow \mathbf{R}^n$  a  $C^\infty$  function such that  $Df_a$  is invertible at  $a \in U$ . Then there exist neighbourhoods  $V, W$  of  $a$  and  $f(a)$  respectively such that  $f(V) = W$  and  $f$  has a  $C^\infty$  inverse on  $W$ .*

**Proof:** By an affine transformation  $x \mapsto Ax + b$  we can assume that  $a = 0$  and  $Df_a = I$ . Now consider  $g(x) = x - f(x)$ . By construction  $Dg_0 = 0$  so by continuity there exists  $r > 0$  such that if  $\|x\| < 2r$ ,

$$\|Dg_x\| < \frac{1}{2}$$

It follows from the mean value theorem that

$$\|g(x)\| \leq \frac{1}{2}\|x\|$$

and so  $g$  maps the closed ball  $\bar{B}(0, r)$  to  $\bar{B}(0, r/2)$ . Now consider

$$g_y(x) = y + x - f(x)$$

(The choice of  $g_y$  is made so that a fixed point  $g_y(x) = x$  solves  $f(x) = y$ ).

If now  $\|y\| \leq r/2$  and  $\|x\| \leq r$ , then

$$\|g_y(x)\| \leq \frac{1}{2}r + \|g(x)\| \leq \frac{1}{2}r + \frac{1}{2}r = r$$

so  $g_y$  maps the complete metric space  $M = \bar{B}(0, r)$  to itself. Moreover

$$\|g_y(x_1) - g_y(x_2)\| = \|g(x_1) - g(x_2)\| \leq \frac{1}{2}\|x_1 - x_2\|$$

if  $x_1, x_2 \in \bar{B}(0, r)$ , and so  $g_y$  is a contraction mapping. Applying Lemma 1 we have a unique fixed point and hence an inverse  $\varphi = f^{-1}$ .

We need to show first that  $\varphi$  is continuous and secondly that it has derivatives of all orders. From the definition of  $g$  and the mean value theorem,

$$\begin{aligned} \|x_1 - x_2\| &\leq \|f(x_1) - f(x_2)\| + \|g(x_1) - g(x_2)\| \\ &\leq \|f(x_1) - f(x_2)\| + \frac{1}{2}\|x_1 - x_2\| \end{aligned}$$

so

$$\|x_1 - x_2\| \leq 2\|f(x_1) - f(x_2)\|$$

which is *continuity* for  $\varphi$ . It follows also from this inequality that if  $y_1 = f(x_1)$  and  $y_2 = f(x_2)$  where  $y_1, y_2 \in B(0, r/2)$  then  $x_1, x_2 \in \bar{B}(0, r)$ , and so

$$\begin{aligned} \|\varphi(y_1) - \varphi(y_2) - (Df_{x_2})^{-1}(y_1 - y_2)\| &= \|x_1 - x_2 - (Df_{x_2})^{-1}(f(x_1) - f(x_2))\| \\ &\leq \|(Df_{x_2})^{-1}\| \|Df_{x_2}(x_1 - x_2) - f(x_1) + f(x_2)\| \\ &\leq A\|x_1 - x_2\|R \end{aligned}$$

where  $A$  is a bound on  $\|(Df_{x_2})^{-1}\|$  and the function  $\|x_1 - x_2\|R$  is the remainder term in the definition of differentiability of  $f$ . But  $\|x_1 - x_2\| \leq 2\|y_1 - y_2\|$  so as  $y_1 \rightarrow y_2$ ,  $x_1 \rightarrow x_2$  and hence  $R \rightarrow 0$ , so  $\varphi$  is differentiable and moreover its derivative is  $(Df)^{-1}$ .

Now we know the derivative of  $\varphi$ :

$$D\varphi = (Df)^{-1}$$

so we see that it is continuous and has as many derivatives as  $f$  itself, so  $\varphi$  is  $C^\infty$ .  $\square$

## 10.2 Existence of solutions of ordinary differential equations

**Lemma 10.3** *Let  $M$  be a complete metric space and  $T : M \rightarrow M$  a map. If  $T^n$  is a contraction mapping, then  $T$  has a unique fixed point.*

**Proof:** By the contraction mapping principle,  $T^n$  has a unique fixed point  $x$ . We also have

$$T^n(Tx) = T^{n+1}x = T(T^n x) = Tx$$

so  $Tx$  is also a fixed point of  $T^n$ . By uniqueness  $Tx = x$ . □

**Theorem 10.4** *Let  $f(t, x)$  be a continuous function on  $|t - t_0| \leq a$ ,  $\|x - x_0\| \leq b$  and suppose  $f$  satisfies a Lipschitz condition*

$$\|f(t, x_1) - f(t, x_2)\| \leq \|x_1 - x_2\|.$$

*If  $M = \sup |f(t, x)|$  and  $h = \min(a, b/M)$ , then the differential equation*

$$\frac{dx}{dt} = f(t, x), \quad x(t_0) = x_0$$

*has a unique solution for  $|t - t_0| \leq h$ .*

**Proof:** Let

$$(Tx)(t) = x_0 + \int_{t_0}^t f(s, x(s)) ds$$

Then  $Tx$  is differentiable since  $f$  and  $x$  are continuous and if  $Tx = x$ ,  $x$  satisfies the differential equation (differentiate the definition). We use the metric space

$$X = \{x \in C([t_0 - h, t_0 + h], \mathbf{R}^n) : \|x(t) - x_0\| \leq Mh\}$$

with the uniform metric

$$d(x_1, x_2) = \sup_{|t-t_0| \leq h} \|x_1(t) - x_2(t)\|$$

which makes it complete. If  $x \in M$ , then  $Tx \in M$  and we claim

$$\|T^k x_1(t) - T^k x_2(t)\| \leq \frac{c^k}{k!} |t - t_0|^k d(x_1, x_2)$$

For  $k = 0$  this is clear, and in general we use induction to establish:

$$\begin{aligned}
\|T^k x_1(t) - T^k x_2(t)\| &\leq \int_{t_0}^t \|f(s, T^{k-1}x_1(s)) - f(s, T^{k-1}x_2(s))\| ds \\
&\leq c \int_{t_0}^t \|T^{k-1}x_1(s) - T^{k-1}x_2(s)\| ds \\
&\leq (c^k/(k-1)!) \int_{t_0}^t |s - t_0|^{k-1} ds d(x_1, x_2) \\
&\leq (c^k/k!) |t - t_0|^k d(x_1, x_2)
\end{aligned}$$

So  $T^n$  is a contraction mapping for large enough  $N$ , and the result follows.  $\square$

**Theorem 10.5** *The solution above depends continuously on the initial data  $x_0$ .*

**Proof:** Take  $h_1 \leq h$  and  $\delta > 0$  such that  $Mh + \delta \leq b$ , and let

$$Y = \{y \in C([t_0 - h_1, t_0 + h_1] \times \bar{B}(x_0, \delta); \mathbf{R}^n) : \|y(t, x) - x\| \leq Mh, y(t_0, x) = x\}$$

which is a complete metric space as before. Now set

$$(Ty)(t, x) = x + \int_{t_0}^t f(s, y(s, x)) ds$$

Since  $Mh_1 + \delta \leq b$ ,  $T$  maps  $Y$  to  $Y$  and just as before  $T^n$  is a contraction mapping with a unique fixed point which satisfies

$$\frac{\partial y}{\partial t} = f(t, y), \quad y(t_0, x) = x$$

Since  $y$  is continuous in  $t$  and  $x$  this is what we need.  $\square$

If  $f(t, x)$  is smooth then we need more work to prove that the solution to the equation is smooth and smoothly dependent on parameters.

### 10.3 Smooth dependence

**Lemma 10.6** *Let  $A(t, x), B(t, x)$  be continuous matrix-valued functions and take  $M \geq \sup_{t,x} \|B\|$ . The solutions of the linear differential equations*

$$\begin{aligned}
\frac{d\xi(t, x)}{dt} &= A(t, x)\xi(t, x), & \xi(t_0, x) &= a(x) \\
\frac{d\eta(t, x)}{dt} &= B(t, x)\eta(t, x), & \eta(t_0, x) &= b(x)
\end{aligned}$$

satisfy

$$\sup_x \|\xi(t, x) - \eta(t, x)\| \leq C\|A - B\| \frac{e^{M|t-t_0|} - 1}{M} + \|a - b\|e^{M|t-t_0|}$$

where  $C$  is a constant depending only on  $A$  and  $a$ .

**Proof:** By the existence theorem we know how to find solutions as limits of  $\xi_n, \eta_n$  where

$$\begin{aligned}\xi_k &= a + \int_{t_0}^t A\xi_{k-1} ds \\ \eta_k &= b + \int_{t_0}^t B\eta_{k-1} ds\end{aligned}$$

Let  $g_k(t) = \sup_x \|\xi_k(t, x) - \eta_k(t, x)\|$  and  $C = \sup_{k,x,t} \|\xi_k\|$ . Then

$$g_n(t) \leq \|a - b\| + C\|A - B\||t - t_0| + M \int_{t_0}^t g_{n-1}(s) ds$$

Now define  $f_n$  by  $f_0(t) = \|a - b\|$  and then inductively by

$$f_n(t) = \|a - b\| + C\|A - B\||t - t_0| + M \int_{t_0}^t f_{n-1}(s) ds$$

Comparing these two we see that  $f_n \geq g_n$ . This is a contraction mapping, so that  $f_n \rightarrow f$  with

$$f(t) = \|a - b\| + C\|A - B\||t - t_0| + M \int_{t_0}^t f(s) ds$$

and solving the corresponding differential equation we get

$$f(t) = \|a - b\|e^{M|t-t_0|} + C\|A - B\| \frac{e^{M|t-t_0|} - 1}{M}$$

As  $g_n(t) \leq f_n(t)$ ,

$$\sup_x \|\xi_n(t, x) - \eta_n(t, x)\| \leq f_n(t)$$

and the theorem follows by letting  $n \rightarrow \infty$ . □

**Theorem 10.7** *If  $f$  is  $C^k$  and*

$$\frac{d}{dt}\alpha(t, x) = f(t, \alpha(t, x)), \quad \alpha(0, x) = x$$

*then  $\alpha$  is also  $C^k$ .*

**Proof:** The hardest bit is  $k = 1$ . Assume  $f$  is  $C^1$  so that  $\partial f/\partial t$  and  $\partial f/\partial x_i$  exist and are continuous. We must show that  $\alpha$  is  $C^1$  in all variables. If that were true, then the matrix valued function  $\lambda$  where ( $\lambda_i = \partial\alpha/\partial x_i$ ) would be the solution of the differential equation

$$\frac{d\lambda}{dt} = D_x f(t, \alpha)\lambda \quad (25)$$

so we shall solve this equation by the existence theorem and prove that the solution is the derivative of  $\alpha$ . Let  $F(s) = f(t, a + s(b - a))$ . Then

$$\frac{dF}{ds} = D_x f(t, a + s(b - a))(b - a)$$

so

$$f(t, b) - f(t, a) = \int_0^1 D_x f(t, a + s(b - a))(b - a) ds$$

But then

$$\begin{aligned} \frac{d}{dt}(\alpha(t, x + y) - \alpha(t, x)) &= f(t, \alpha(t, x + y)) - f(t, \alpha(t, x)) \\ &= \int_0^1 D_x f(t, \alpha(t, x) + s(\alpha(t, x + y) - \alpha(t, x)))(\alpha(t, x + y) - \alpha(t, x)) ds \end{aligned}$$

Let  $A(t, x) = D_x f(t, \alpha(t, x))$  and  $\xi(t, x) = \lambda(t, x)y$  and

$$B_y(t, x) = \int_0^1 D_x f(t, \alpha(t, x) + s(\alpha(t, x + y) - \alpha(t, x))) ds, \quad \eta_y(t, x) = \alpha(t, x + y) - \alpha(t, x)$$

Apply the previous lemma and we get

$$\sup_{|t| \leq \epsilon} \|\lambda(t, x)y - (\alpha(t, x + y) - \alpha(t, x))\| = o(\|y\|)$$

and so  $D_x \alpha = \lambda$ , which is continuous in  $(t, x)$ . Since also  $d\alpha/dt = f(t, \alpha)$  this means that  $\alpha$  is  $C^1$  in all variables.

To continue, suppose inductively that the theorem is true for  $k - 1$ , and  $f$  is  $C^k$ . Then  $A(t, x) = D_x f(t, \alpha(t, x))$  is  $C^{k-1}$  but since

$$\frac{d\lambda}{dt} = A\lambda$$

we have  $\lambda$  is  $C^{k-1}$ . Now  $D_x \alpha = \lambda$  so the  $x_i$ -derivatives of  $\alpha$  are  $C^{k-1}$ . But also  $d\alpha/dt = f(t, \alpha)$  is  $C^{k-1}$  too, so  $\alpha$  is  $C^k$ .  $\square$

## 10.4 Partitions of unity on general manifolds

**Definition 39** A partition of unity on  $M$  is a collection  $\{\varphi_i\}_{i \in I}$  of smooth functions such that

- $\varphi_i \geq 0$
- $\{\text{supp } \varphi_i : i \in I\}$  is locally finite
- $\sum_i \varphi_i = 1$

Here *locally finite* means that for each  $x \in M$  there is a neighbourhood  $U$  which intersects only finitely many supports  $\text{supp } \varphi_i$ .

**Theorem 10.8** Given any open covering  $\{V_\alpha\}$  of  $M$  there exists a partition of unity  $\{\varphi_i\}$  on  $M$  such that  $\text{supp } \varphi_i \subset V_{\alpha(i)}$  for some  $\alpha(i)$ .

**Proof:** (by exhaustion – !)

1.  $M$  is locally compact since each  $x \in M$  has a neighbourhood homeomorphic to, say, the open unit ball in  $\mathbf{R}^n$ . So take  $U$  homeomorphic to a smaller ball, then  $\bar{U}$  is compact. Since  $M$  is Hausdorff,  $\bar{U}$  is closed (compact implies closed in Hausdorff spaces).

2.  $M$  has a countable basis of open sets  $\{U_j\}_{j \in \mathbf{N}}$ , so  $x \in U_j \subset U$  and  $\bar{U}_j \subset \bar{U}$  is compact so  $M$  has a countable basis of open sets with  $\bar{U}_j$  compact.

3. Put  $G_1 = U_1$ . Then

$$\bar{G}_1 \subset \bigcup_{j=1}^{\infty} U_j$$

so by compactness there is  $k > 1$  such that

$$\bar{G}_1 \subset \bigcup_{j=1}^k U_j = G_2$$

Now take the closure of  $G_2$  and do the same. We get compact sets  $\bar{G}_j$  with

$$\bar{G}_j \subset G_{j+1} \quad M = \bigcup_{j=1}^{\infty} U_j$$

4. By construction we have

$$\bar{G}_j \setminus G_{j-1} \subset G_{j+1} \setminus \bar{G}_{j-2}$$

and the set on the left is compact and the one on the right open. Now take the given open covering  $\{V_\alpha\}$ . The sets  $V_\alpha \cap (G_{j+1} \setminus \bar{G}_{j-2})$  cover  $\bar{G}_j \setminus G_{j-1}$ . This latter set is compact so take a finite subcovering, and then proceed replacing  $j$  with  $j+1$ . This process gives a countable locally finite *refinement* of  $\{V_\alpha\}$ , i.e. each  $V_\alpha \cap (G_{j+1} \setminus \bar{G}_{j-2})$  is an open subset of  $V_\alpha$ . It is locally finite because

$$G_{j+1} \setminus \bar{G}_{j-2} \cap G_{j+4} \setminus \bar{G}_{j+1} = \emptyset$$

5. For each  $x \in M$  let  $j$  be the largest natural number such that  $x \in M \setminus \bar{G}_j$ . Then  $x \in V_\alpha \cap (G_{j+2} \setminus \bar{G}_{j-1})$ . Take a coordinate system within this open set and a bump function  $f$  which is identically 1 in a neighbourhood  $W_x$  of  $x$ .

6. The  $W_x$  cover  $\bar{G}_{j+1} \setminus G_j$  and so as  $x$  ranges over the points of  $G_{j+2} \setminus \bar{G}_{j-1}$  we get an open covering and so by compactness can extract a finite subcovering. Do this for each  $j$  and we get a countable collection of smooth functions  $\psi_i$  such that  $\psi_i \geq 0$  and, since the set of supports is locally finite,

$$\psi = \sum \psi_i$$

is well-defined as a smooth function on  $M$ . Moreover

$$\text{supp } \psi_i \subset V_\alpha \cap (G_m \setminus \bar{G}_{m-3}) \subset V_\alpha$$

so each support is contained in a  $V_\alpha$ . Finally define

$$\varphi_i = \frac{\psi_i}{\psi}$$

then this is the required partition of unity. □

## 10.5 Sard's theorem (special case)

**Theorem 10.9** *Let  $M$  and  $N$  be differentiable manifolds of the same dimension  $n$  and suppose  $F : M \rightarrow N$  is a smooth map. Then the set of critical values of  $F$  has measure zero in  $N$ . In particular, every smooth map  $F$  has at least one regular value.*



**Proof:** Since a countable union of null sets (=sets of measure zero) is null, and  $M$  and  $N$  have a countable basis of open sets, it suffices to consider the local case of  $F : U \rightarrow \mathbf{R}^n$ . Moreover since  $U$  is a countable union of compact cubes we need only prove that the image of the set of critical points in the compact cube  $K = \{x \in \mathbf{R}^n : |x_i| \leq 1\}$  is of measure zero.

Now suppose  $a \in K$  is a critical point, so that the image of  $DF_a$  is contained in a proper subspace of  $\mathbf{R}^n$ , and so is annihilated by a linear form  $f$ . Let  $H \subset \mathbf{R}^n$  be the hyperplane  $f(x - F(a)) = 0$ . Then

$$d(F(x), H) \leq \|F(x) - (F(a) + DF_a(x - a))\| \quad (26)$$

On the other hand since  $F$  is  $C^\infty$ , from Taylor's theorem we have a constant  $C$  such that

$$\|F(x) - F(y) - DF_y(x - y)\| \leq C\|x - y\|^2$$

for all  $x, y \in K$ , since  $K$  is compact. Substituting in (26) this yields

$$d(F(x), H) \leq C\|x - a\|^2$$

If  $\|x - a\| \leq \eta$ , then  $d(F(x), H) \leq C\eta^2$ . Let  $M = \sup\{\|DF_x\| : x \in K\}$ , then by the mean value theorem

$$\|F(x) - F(a)\| \leq M\|x - a\|$$

for  $x, a \in K$  and so  $d(F(x), F(a)) \leq M\eta$ . Thus  $F(x)$  lies in the intersection of a slab of thickness  $2C\eta^2$  around  $H$  and a ball of radius  $M\eta$  centred on  $F(a)$ . Putting the ball in a cube of side  $2M\eta$ , the volume of this intersection is less than

$$2C\eta^2(2M\eta)^{n-1} = 2^n CM^{n-1}\eta^{n+1}$$

Now subdivide the cube into  $N^n$  cubes of side  $1/N$ , and repeat the argument for each cube. Since now  $\|x - y\| \leq \sqrt{n}/N$ , critical points in this cube lie in a volume less than

$$2^n CM^{n-1} \left(\frac{\sqrt{n}}{N}\right)^{n+1}$$

Since there are at most  $N^n$  such volumes, the total is less than

$$(2^n M^{n-1} C n^{(n+1)/2}) N^{-1}$$

which tends to zero as  $N \rightarrow \infty$ .

Thus the set of critical values is of measure zero. □