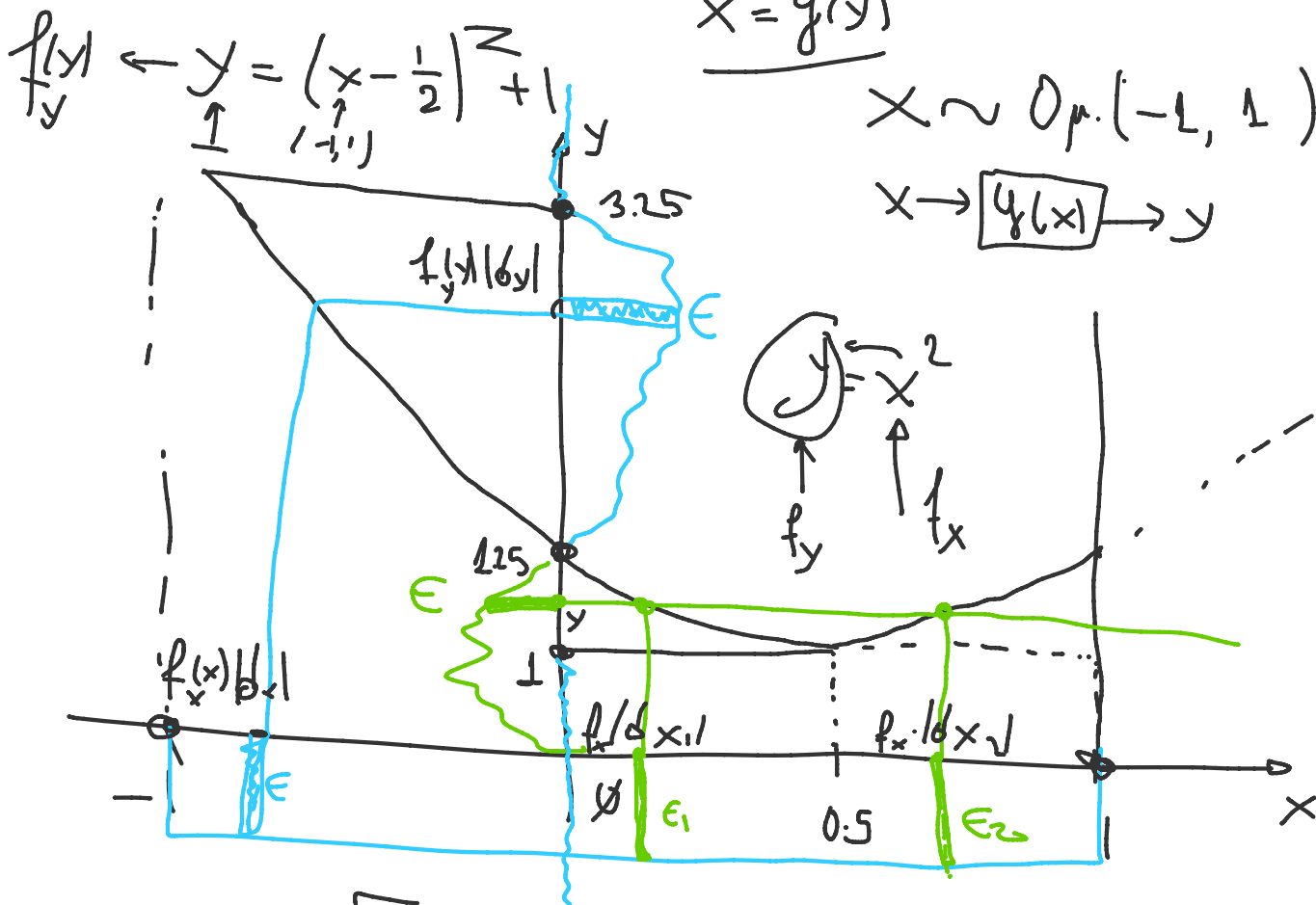


$$x = y^{-1/2}$$

$$x \sim \text{Op.}(-1, 1)$$

$$x \rightarrow \boxed{y(x)} \rightarrow y$$



$$x_1 = -\frac{2\sqrt{y-1}-1}{2}$$

$$x_2 = \frac{2\sqrt{y-1}+1}{2}$$

$$\frac{dx_1}{dy} = -\frac{1}{2\sqrt{y-1}}$$

$$\frac{dx_2}{dy} = \frac{1}{2\sqrt{y-1}}$$

$$\boxed{\epsilon = \epsilon_1 + \epsilon_2}$$

$$\Rightarrow f_y(y) \frac{dy}{|dy|} = f_x(x_1) \frac{dx_1}{|dy|} + f_x(x_2) \frac{dx_2}{|dy|}$$

$$\frac{1}{4\sqrt{y-1}}, \quad 1.25 \leq y \leq 3.25$$

$$-1 < x < 1$$

$$f_y(y) = \begin{cases} \frac{1}{2\sqrt{y-1}}, & 1 < y < 1.25 \end{cases}$$

$$y = x_1 \cdot x_2$$

φ, φ<sub>2D</sub>

$$y = x_1 + x_2 \Rightarrow f_y(y) = f_{x_1}(x_1) \otimes f_{x_2}(x_2)$$

Πολυδιάστατη Gaussian

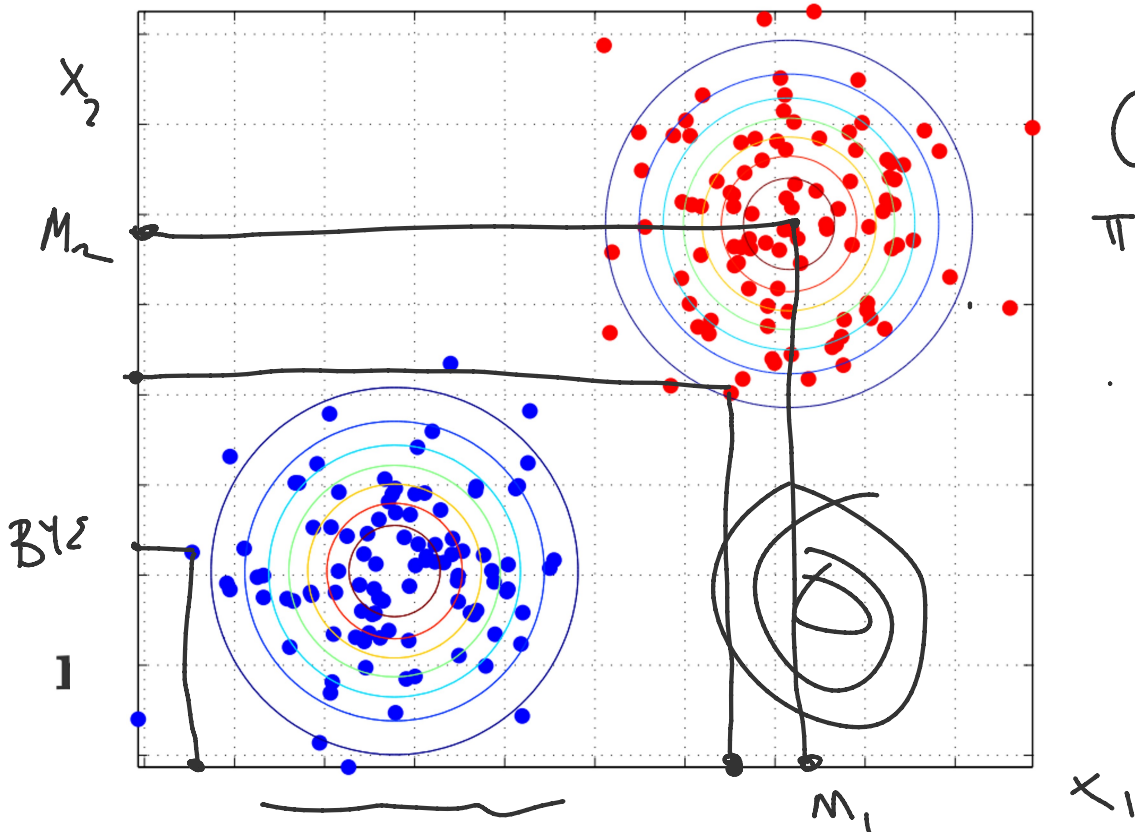
$$P(\mathbf{x}; \mathbf{m}, \mathbf{C}) = \frac{1}{2\pi^{k/2} |\mathbf{C}|^{1/2}} e^{-(\mathbf{x}-\mathbf{m})^T \mathbf{C}^{-1} (\mathbf{x}-\mathbf{m})}$$

k = 2

$$\mathbf{m} = \begin{bmatrix} m_1 \\ m_2 \end{bmatrix}$$

$$\mathbf{C} = \begin{bmatrix} \sigma^2 & \phi \\ \phi & \sigma^2 \end{bmatrix}$$

πσ<sup>2</sup>



$$\mathbf{C} = \frac{1}{n} \sum (\mathbf{x} - \mathbf{m})(\mathbf{x} - \mathbf{m})^T$$

$$\mathbf{C} = \frac{1}{N-1} (\mathbf{x} - \mathbf{m})^T \cdot (\mathbf{x} - \mathbf{m})$$

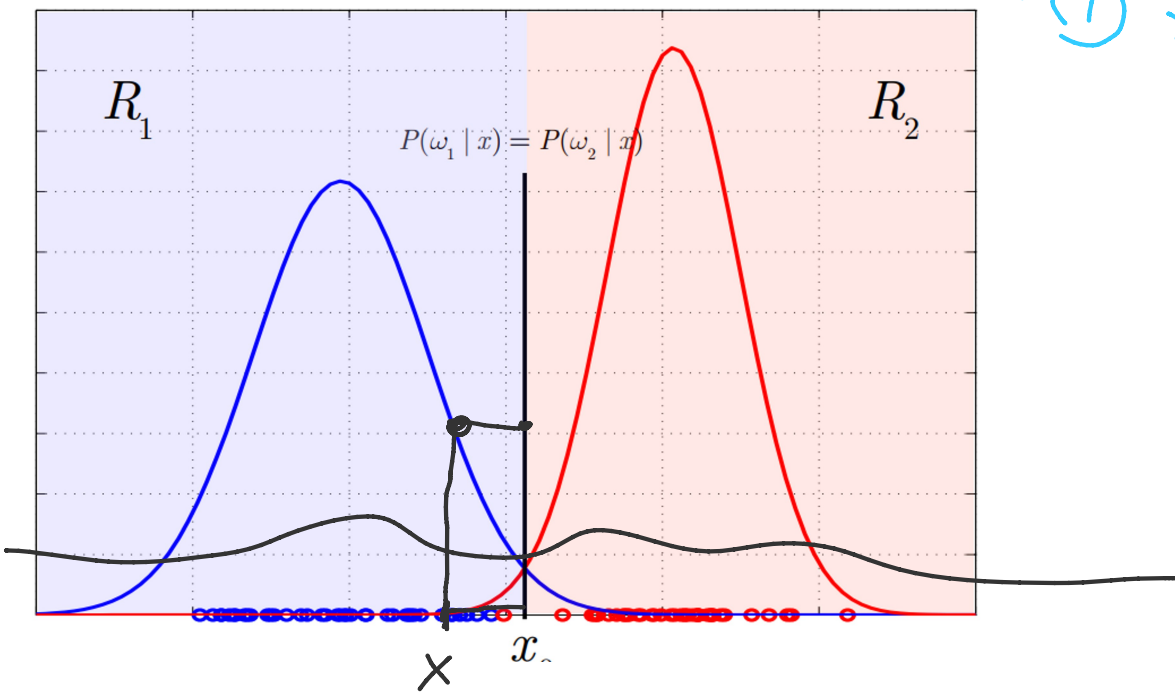
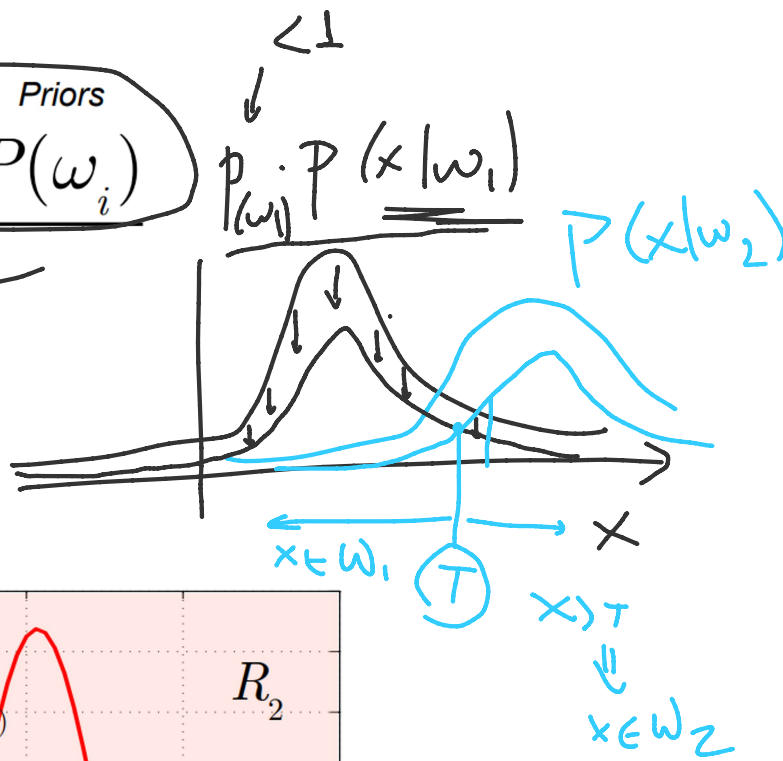
$$\underline{\mathbf{m}} = \frac{1}{N} \sum_{i=1}^N \underline{x}_i$$

Ταξινόμηση

$$P(\omega_i | \underline{x}) = \frac{\text{Likelihood} \cdot \text{Priors}}{\text{Evidence}} = \frac{P(\underline{x} | \omega_i) P(\omega_i)}{P(\underline{x})}$$

$\omega_1 = \text{Πορ}$

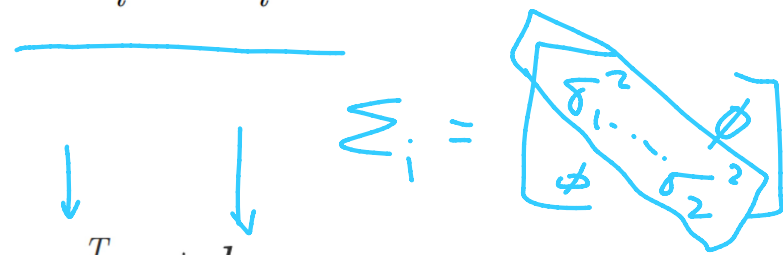
$\omega_2 = \text{ΒΥΣ}$



Υπόθεση

$$\Sigma_i = \sigma_i^2 \mathbf{I} \Rightarrow \text{ΓΡΑΜΜΙΚΟΙ ΤΑΞΙΝΟΜΗΤΕΣ}$$

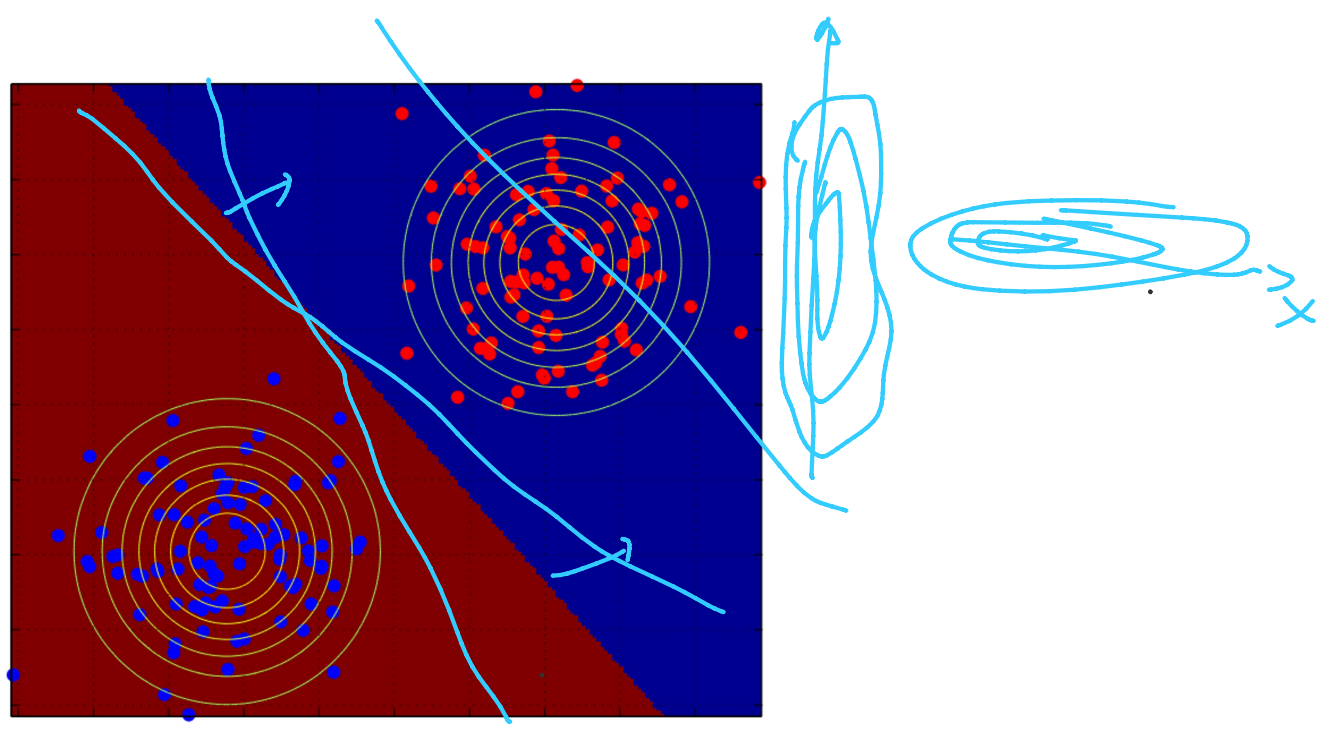
$\mu_i = \sigma_i \mathbf{1}$



$$g_i(\mathbf{x}) = \mathbf{w}_i^T \mathbf{x} + b$$

$$\mathbf{w}_i = \boldsymbol{\mu}_i / \sigma^2$$

$$b = -\frac{\boldsymbol{\mu}_i^T \boldsymbol{\mu}_i}{2\sigma^2} + \log P(\omega_i)$$



Τυχαίος Πίνακας συνδιασπορών δημιουργεί μη γραμμικές περιοχές



$$g_i(\mathbf{x}) = \mathbf{x}^T \mathbf{W}_i \mathbf{x} + \mathbf{w}_i^T \mathbf{x} + w_i$$

$$\mathbf{W}_i = -\frac{1}{2} \boldsymbol{\Sigma}_i^{-1}$$

$$\dots = \boldsymbol{\Sigma}_i^{-1} \dots$$

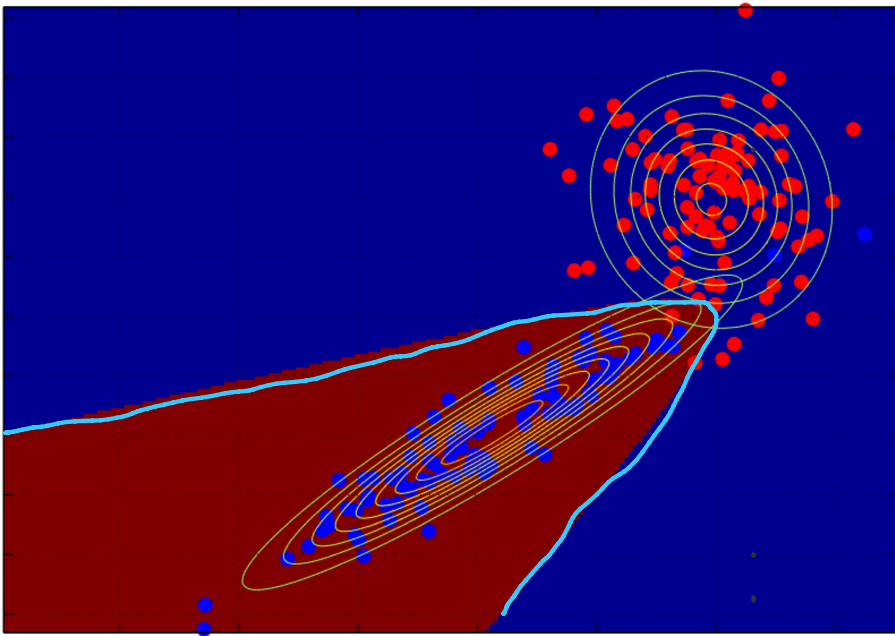
$$g_i(\mathbf{x}) = \mathbf{x}^T \mathbf{W}_i \mathbf{x} + \mathbf{w}_i^T \mathbf{x} + w_i$$

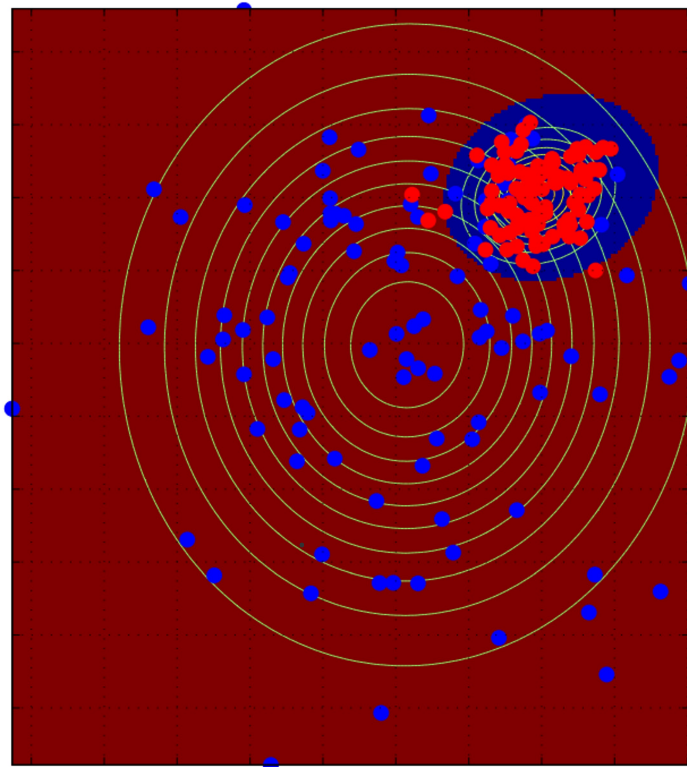
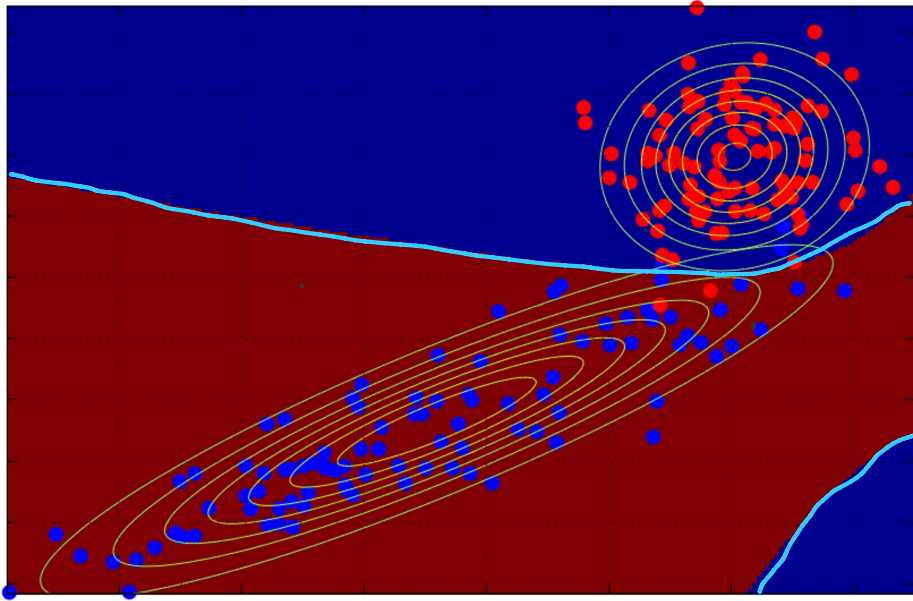
$$\mathbf{W}_i = -\frac{1}{2} \boldsymbol{\Sigma}_i^{-1}$$

$$\mathbf{w}_i = \boldsymbol{\Sigma}_i^{-1} \boldsymbol{\mu}_i$$

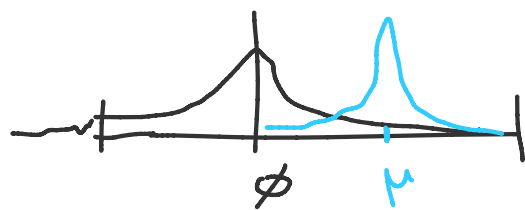
$$w_i = -\frac{1}{2} \boldsymbol{\mu}_i^T \boldsymbol{\Sigma}_i^{-1} \boldsymbol{\mu}_i - \frac{1}{2} \log |\boldsymbol{\Sigma}_i|$$

+ log P( $\omega_i$ )





$$\Delta \rightarrow \frac{\alpha}{2} x_1^2 + \frac{\beta}{2} x_2^2 + \gamma x_1 x_2 + \frac{\mu}{2} x_1 + \frac{\nu}{2} x_2 + \frac{\phi}{2}$$



$$\rho^{(N)} = \int_{x \in \mathcal{P}} x^N f_x(x) dx$$

$\phi, \mu$   
 $\sigma^2, \sigma^2$

$$f_x(x) = \frac{1}{\sigma \sqrt{2\pi}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$$

$\sigma^2$

$\mu, \sigma$   
 $\Gamma \text{H} \Gamma \text{H}$

$$f_{\phi}(x) = G(x, \phi, \sigma^2) \quad x \in \mathbb{R}$$

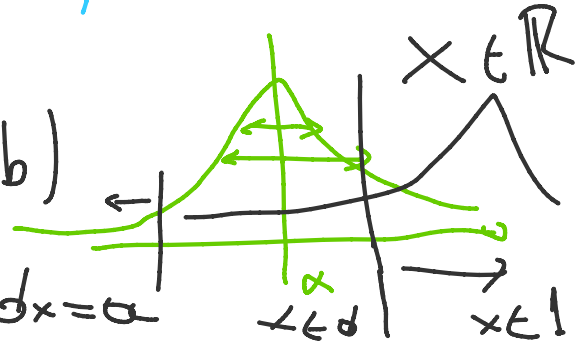
$$f_1(x) = G(x, \mu, \sigma_1^2) \quad \text{ΔΕΚΤΗΣ}$$

Συνάρτηση πλ: Cauchy

$$\frac{b}{\pi((x-a)^2 + b^2)}$$

$$= C(x, a, b)$$

$$\int_{-\infty}^{+\infty} C(x, a, b) dx = 1$$



ΣΤΟΝ ΔΕΚΤΗ:

$$f_0(x) = P(x|\phi) = C(x, \phi, 1)$$

$$f_1(x) = P(x|1) = C(x, 1, 2)$$

$$P(\phi) = \frac{1}{2}$$

Στοιχ δέκτη εξαβα x  $P(\phi) = P(1) = \frac{1}{2}$

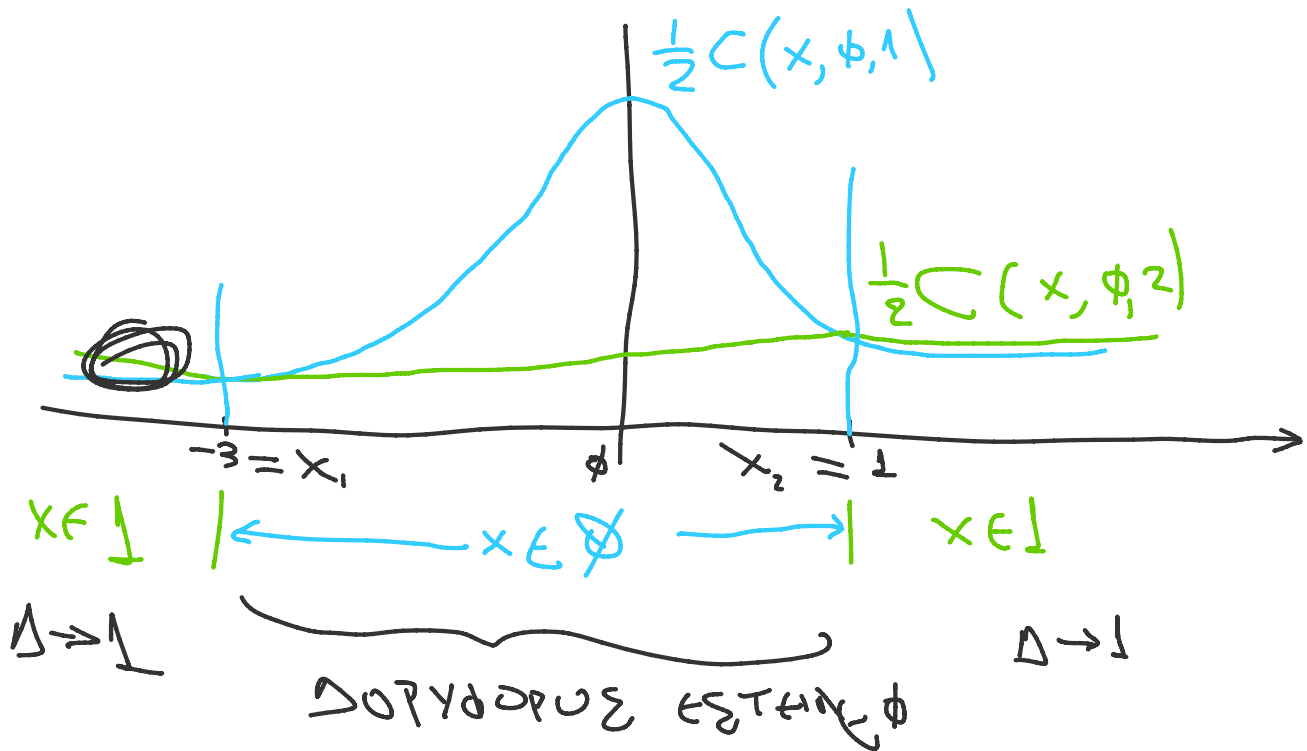
$$\frac{P(\phi|x) > P(1|x)}{\Rightarrow} \frac{P(x|\phi) \cdot P(\phi)}{P(x)} > \frac{P(x|1) \cdot P(1)}{P(x)}$$

$$\Rightarrow P(x|\phi) > P(x|1) \Rightarrow f_0(x) > f_1(x)$$

$$\Rightarrow C(x, \phi, 1) > C(x, 1, 2) \Rightarrow$$

$$\frac{1}{\pi(x^2+1)} = \frac{2}{\pi((x-1)^2+4)} \Rightarrow \begin{cases} x = -3 \\ x = 1 \end{cases}$$

$$\frac{\pi(x^2+1)}{\pi((x-1)^2+4)} \Rightarrow \underbrace{\underbrace{x=1}}_{\text{pole}}$$



$$X_v \frac{P(\phi)}{P(\mathbb{I})} = k \neq 1 \Rightarrow \underbrace{C_\phi(x, \phi, 1) \cdot k = \mathcal{G}(x, 1, 2)}$$

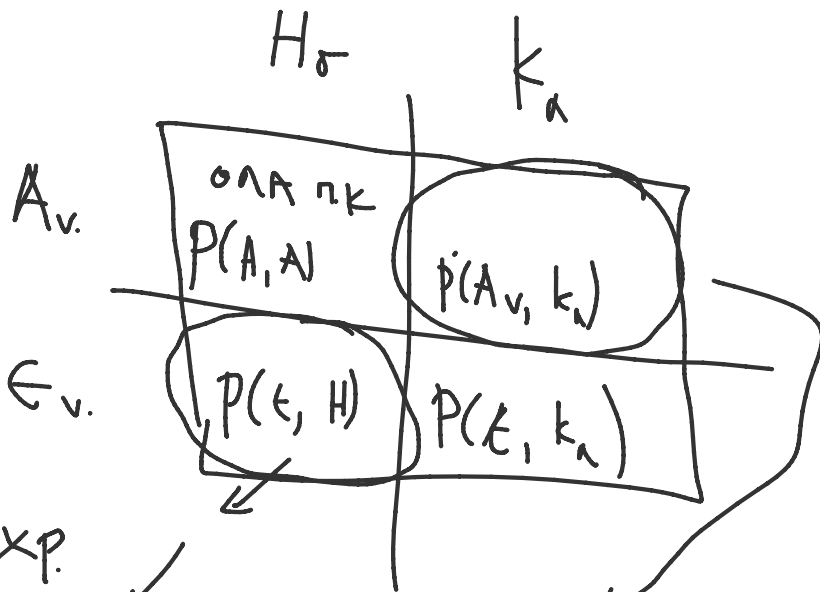
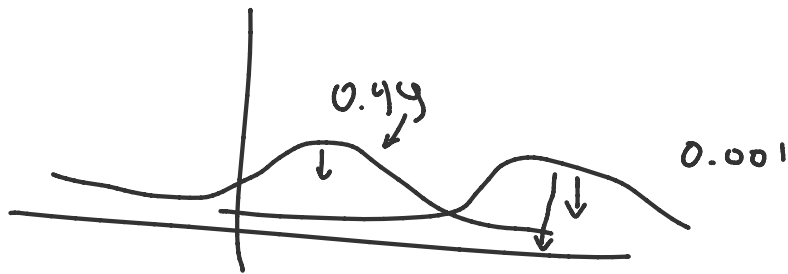
$$x_1 = -\frac{2\sqrt{-k^2+3k-1}-k}{k-2}, x_2 = \frac{2\sqrt{-k^2+3k-1}+k}{k-2}$$

$$\Delta = -k^2+3k-1 > 0 \Rightarrow \underline{-\frac{\sqrt{13}+3}{2} < k < \frac{\sqrt{13}-3}{2}}$$

$$\underline{0 < k < \frac{\sqrt{13}-1}{2}}$$



$$C_0(x, \alpha_1, b_1) \cdot p(d) > C_1(x, \alpha_2, b_2) \cdot p(i)$$



$$K_{EH} \cdot P(E, H) + K_{AK} \cdot P(A, K_A) = Q(S_1)$$

$$S_{\text{best}} = \text{argmin } Q(S_1)$$

$$K_{EH} \cdot P(x | H_0) \cdot P(H_0) + K_{AK} \cdot P(x | H_1) \cdot P(H_1)$$

$$\underbrace{k_{EH} f(x|H_0) \cdot p(H_0)}_{\downarrow} > \underbrace{k_{AK} f(x|K_n) \cdot p(K_n)}_{\downarrow}$$

$$P(\omega_1 | x_i) > P(\omega_2 | x_i) \Rightarrow S_1$$

$$\underbrace{P(\omega_1, \omega_2) + P(\omega_2, \omega_1)}_{\text{Ansatz}} \Rightarrow S_1$$